

Claim: If a is a solution of $F(x) \sqsubseteq x$ then $F^k(\perp) \sqsubseteq a$ for all k .

By induction: Clearly $\perp \sqsubseteq a$

Further if $F^k(\perp) \sqsubseteq a$ then by **monotonicity** we have
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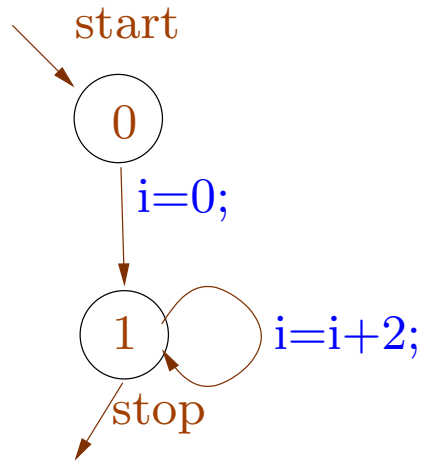
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Hence if $F^{k+1}(\perp) = F^k(\perp)$ for any k then $F^k(\perp)$ is **least solution** of $F(x) \sqsubseteq x$.

Such a k always exists if the lattice is finite.

What in case of infinite lattices?



Constraint system:

$$\mathcal{V}[0] \supseteq \mathbb{Z}$$

$$\mathcal{V}[1] \supseteq \{0\} \cup \{x+2 \mid x \in \mathcal{V}[1]\}$$

The least solution:

$$\mathcal{V}[0] = \mathbb{Z} \text{ and } \mathcal{V}[1] = \{2n \mid n \geq 0\}.$$

Iteration doesn't terminate:

	\perp	$F(\perp)$	$F^2(\perp)$	$F^3(\perp)$	
$\mathcal{V}[0]$	\emptyset	\mathbb{Z}	\mathbb{Z}	\mathbb{Z}	...
$\mathcal{V}[1]$	\emptyset	$\{0\}$	$\{0, 2\}$	$\{0, 2, 4\}$	

Existence of least solutions: Knaster-Tarski

Fact: In a complete lattice \mathbb{D} , every monotone function $f : \mathbb{D} \rightarrow \mathbb{D}$ has a **least fixpoint** a .

Fixpoint: an element x such that $f(x) = x$.

Prefixpoint: an element x such that $f(x) \sqsubseteq x$.

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Let $P = \{x \in \mathbb{D} \mid f(x) \sqsubseteq x\}$ (the set of prefixpoints).

The least fixpoint of f is $a = \bigsqcap P$.

(1) $a \in P$:

$$f(a) \sqsubseteq f(d) \sqsubseteq d \text{ for all } d \in P.$$

$$\implies f(a) \text{ is a lower bound of } P.$$

$$\implies f(a) \sqsubseteq a.$$

\implies a is the least prefixpoint.

(2) $f(a) = a$:

$f(a) \sqsubseteq a$, from (1)

$\implies f^2(a) \sqsubseteq f(a)$, by monotonicity

$\implies f(a) \in P$

$\implies a \sqsubseteq f(a)$

Hence a is the least prefixpoint and is also a fixpoint.

Hence a is also the least fixpoint.

Example 1: Consider partial order $\mathbb{D}_1 = \mathbb{N}$ with $0 \sqsubseteq 1 \sqsubseteq 2 \sqsubseteq \dots$

The function $f(x) = x+1$ is monotonic.

However it has no fixpoint.

Actually \mathbb{D}_1 is not a complete lattice.

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Example 2: Now we consider $\mathbb{D}_2 = \mathbb{N} \cup \{\infty\}$.

This is a complete lattice.

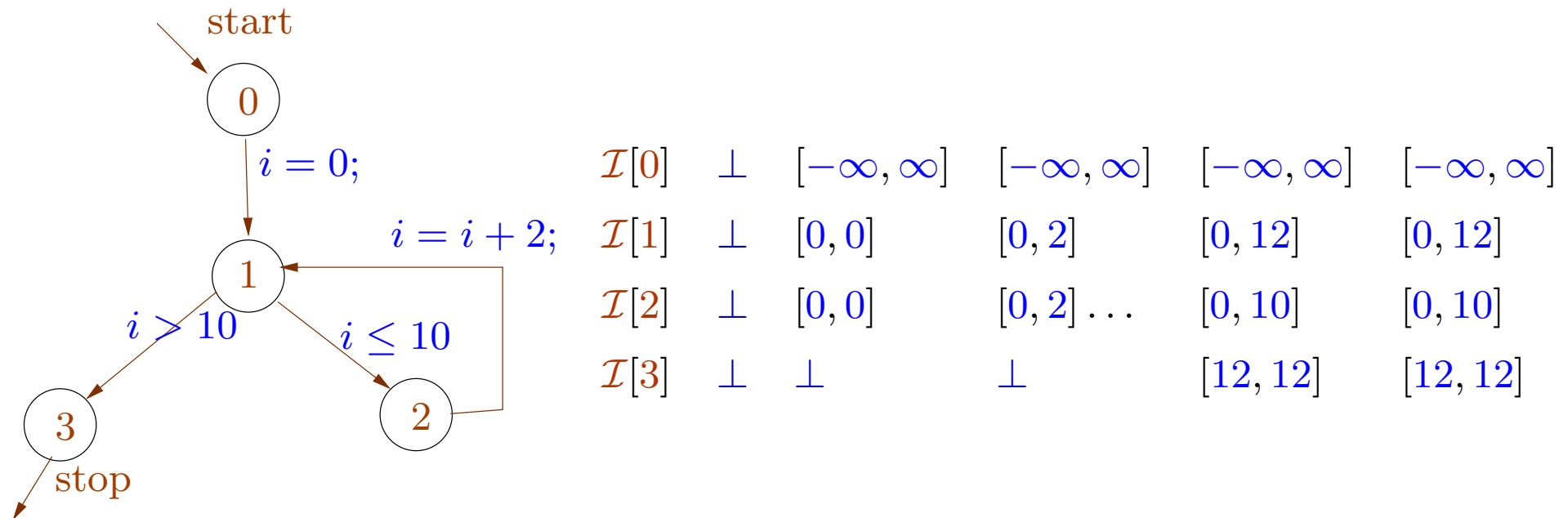
The function $f(x) = x+1$ is again monotonic.

The only fixpoint is ∞ : $\infty+1 = \infty$.

Abstract Interpretation: Cousot, Cousot 1977

We use a suitable complete lattice as the domain of abstract values.

Example: **intervals** as abstract values:



The analysis **guarantees** e.g. that at node **1** the value of i is always in the interval $[0, 12]$.

We have the set of concrete states $\mathcal{S} = (\text{Vars} \rightarrow \mathbb{Z})$.

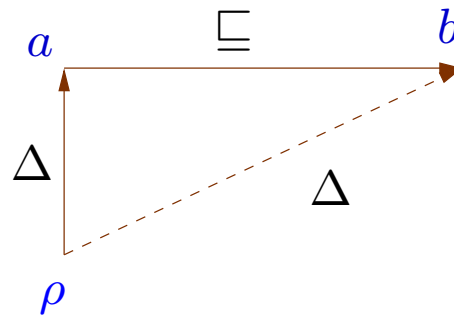
We choose a complete lattice \mathbb{D} of abstract states.

We define an abstraction relation

$$\Delta : \mathcal{S} \times \mathbb{D}$$

with the condition that

$$\rho \Delta a \wedge a \sqsubseteq b \implies \rho \Delta b$$



The concretization function: $\gamma(a) = \{\rho \mid \rho \Delta a\}$.

Example: For a program on two integer variables, $\mathbf{Vars} = \{x, y\}$.

The concrete states are from the set $\mathcal{S} = (\mathbf{Vars} \rightarrow \mathbb{Z})$ (or equivalently \mathbb{Z}^2).

For **interval analysis**, we choose the **complete lattice**

$$\mathbb{D}_{\mathbb{I}} = (\mathbf{Vars} \rightarrow \mathbb{I})_{\perp} = (\mathbf{Vars} \rightarrow \mathbb{I}) \cup \{\perp\}$$

where $\mathbb{I} = \{[l, u] \mid l \in \mathbb{Z} \cup \{-\infty\}, u \in \mathbb{Z} \cup \{\infty\}, l \leq u\}$ is the set of intervals.



Partial order on \mathbb{I} : $[l_1, u_1] \sqsubseteq [l_2, u_2]$ iff $l_1 \geq l_2$ and $u_1 \leq u_2$

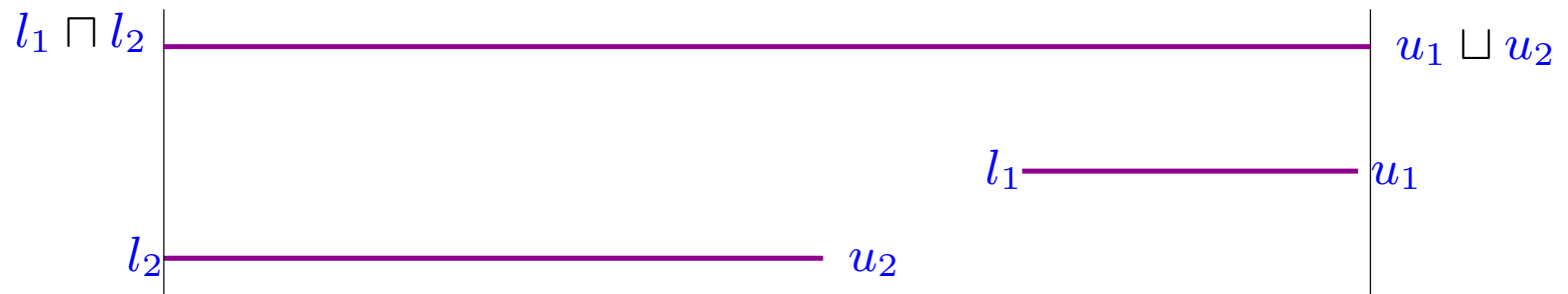
(As usual, $-\infty \sqsubseteq n \sqsubseteq \infty$ for all $n \in \mathbb{Z}$.)

Partial order on $\mathbf{Vars} \rightarrow \mathbb{I}$: $D_1 \sqsubseteq D_2$ iff $D_1(x) \sqsubseteq D_2(x)$.

Extension to $(\mathbf{Vars} \rightarrow \mathbb{I})_{\perp}$: $\perp \sqsubseteq D$ for all D .

$(\mathbf{Vars} \rightarrow \mathbb{I})_{\perp}$ is a complete lattice. $(\mathbf{Vars} \rightarrow \mathbb{I})$ is not.

In particular we define $[l_1, u_1] \sqcup [l_2, u_2] = [l_1 \sqcap l_2, u_1 \sqcup u_2]$.



\perp represents the “unreachable state”: maps every variable to the “empty interval”.

The abstraction relation:

$$\rho \Delta D \text{ iff } D \neq \perp \text{ and } \rho(x) \Delta D(x).$$

where $n \Delta [l, u]$ iff $l \leq n \leq u$.

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This satisfies the required condition:

Suppose $\rho \Delta D_1$ and $D_1 \sqsubseteq D_2$.

$\implies D_1 \neq \perp$ and $D_2 \neq \perp$.

$\rho(x) \Delta D_1(x)$ and $D_1(x) \sqsubseteq D_2(x)$ for each x .

$\implies \rho(x) \Delta D_1(x)$ for each x .



The concretization function:

$$\gamma(\perp) = \{\}$$

$$\gamma(D) = \{\rho \mid \rho(x) \Delta D(x)\}, \quad \text{for } D \neq \perp$$

$$\begin{aligned} \gamma(\{x \mapsto [3, 5], y \mapsto [0, 7]\}) = & \quad \{\{x \mapsto 3, y \mapsto 0\}, \{x \mapsto 3, y \mapsto 1\}, \\ & \quad \dots \{x \mapsto 3, y \mapsto 7\} \\ & \quad \dots \{x \mapsto 5, y \mapsto 0\} \dots \{x \mapsto 5, y \mapsto 7\}\} \end{aligned}$$

Abstraction of the partial transformation induced by edges.

Recall the edges $k = (u, l, v)$ induce a partial transformation on concrete states:

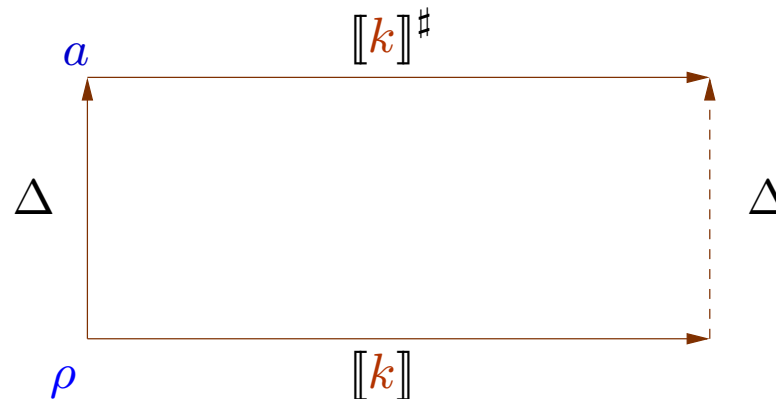
$$\llbracket k \rrbracket = \llbracket l \rrbracket : \mathcal{S} \rightarrow \mathcal{S}$$

Now on our chosen domain \mathbb{D} we define a monotonic abstract transformation:

$$\llbracket k \rrbracket^\# = \llbracket l \rrbracket^\# : \mathbb{D} \rightarrow \mathbb{D}$$

The abstract transformation should simulate the concrete transformation:

if $\rho \Delta a$ and $\llbracket l \rrbracket \rho$ is defined then $\llbracket l \rrbracket \rho \Delta \llbracket l \rrbracket^\# a$.



Abstract transformation for interval analysis.

For concrete operators \square we define **monotonic** abstract operators $\square^\#$ such that

$$x_1 \Delta a_1 \wedge \dots \wedge x_n \Delta a_n \implies \square(x_1, \dots, x_n) \Delta \square^\#(a_1, \dots, a_n)$$

addition:

$$\begin{aligned} [l_1, u_1] +^\# [l_2, u_2] &= [l_1 + l_2, u_1 + u_2]. \\ - + \infty &= \infty \\ - + -\infty &= \infty \\ // \infty + -\infty &\text{ is undefined.} \end{aligned}$$

subtraction:

$$-^\# [l, u] = [-u, -l]$$

Multiplication: $[l_1, u_1] *^\# [l_2, u_2] = [m, n]$ where

$$m = l_1 l_2 \sqcap l_1 u_2 \sqcap l_2 u_1 \sqcap l_2 u_2$$

$$n = l_1 l_2 \sqcup l_1 u_2 \sqcup l_2 u_1 \sqcup l_2 u_2$$

Example:

$$[1, 3] *^\# [5, 8] = [5, 24]$$

$$[-1, 3] *^\# [5, 8] = [-8, 24]$$

$$[-1, 3] *^\# [-5, 8] = [-15, 24]$$

$$[-1, 3] *^\# [-5, -8] = [-24, 5]$$

Equality test:

$$[l_1, u_1] ==^\# [l_2, u_2] = \begin{cases} [1, 1] & \text{if } l_1 = u_1 = l_2 = u_2 \\ [0, 0] & \text{if } u_1 < l_2 \text{ or } u_2 < l_1 \\ [0, 1] & \text{otherwise} \end{cases}$$

Example:

$$\begin{aligned} [7, 7] & ==^\# [7, 7] & = [1, 1] \\ [1, 7] & ==^\# [9, 12] & = [0, 0] \\ [1, 7] & ==^\# [1, 7] & = [0, 1] \end{aligned}$$

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$$\begin{aligned} [1, 7] <^{\#} [9, 12] &= [1, 1] \\ [9, 12] <^{\#} [1, 7] &= [0, 0] \\ [1, 7] <^{\#} [6, 8] &= [0, 1] \end{aligned}$$

Monotonic abstract evaluation of expressions

For $D \neq \perp$,

$$\llbracket x \rrbracket^\# D = D(x)$$

$$\llbracket n \rrbracket^\# D = [n, n]$$

$$\llbracket \square(e_1, \dots, e_n) \rrbracket^\# D = \square^\#(\llbracket e_1 \rrbracket^\# D, \dots, \llbracket e_n \rrbracket^\# D)$$

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$$\text{Fact: } \rho \Delta D \text{ and } \llbracket e \rrbracket \rho \text{ is defined} \implies \llbracket e \rrbracket \rho \Delta \llbracket e \rrbracket^\# D.$$

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Case e is x : since $\rho \Delta D$ hence $\llbracket x \rrbracket \rho = \rho(x) \Delta D(x) = \llbracket x \rrbracket^\# D$

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$$\text{Case } e \text{ is } \square(e_1, \dots, e_n): \quad \text{since each } \llbracket e_i \rrbracket \rho \Delta \llbracket e_i \rrbracket^\# D \text{ hence}$$

$$\llbracket \square(e_1, \dots, e_n) \rrbracket \rho = \square(\llbracket e_1 \rrbracket \rho, \dots, \llbracket e_n \rrbracket \rho)$$

Δ

$$\square^\#(\llbracket e_1 \rrbracket^\# D, \dots, \llbracket e_n \rrbracket^\# D) = \llbracket \square^\#(e_1, \dots, e_n) \rrbracket^\# D$$

Finally, the **monotonic** abstract transformations induced by edges

$$\begin{aligned} & \llbracket l \rrbracket^\# \perp = \perp \\ \text{For } D \neq \perp, & \llbracket ; \rrbracket^\# D = D \\ & \llbracket x = e; \rrbracket^\# D = D \oplus \{x \mapsto \llbracket e \rrbracket^\# D\} \\ & \llbracket e \rrbracket^\# D = \begin{cases} \perp & \text{if } \llbracket e \rrbracket^\# D = [0, 0] \\ D & \text{otherwise} \end{cases} \end{aligned}$$

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Next we must check the condition:

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Clearly $D \neq \perp$ here.

To check: $\rho \Delta D \wedge \llbracket l \rrbracket \rho = \rho_1 \wedge \llbracket l \rrbracket^\# D = D_1 \implies \rho_1 \Delta D_1.$

Case l is ;

$$\rho_1 = \rho \Delta D = D_1.$$

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Case e is some condition e

Since the transformation $\llbracket e \rrbracket \rho$ is defined,

hence the expression evaluation $\llbracket e \rrbracket \rho \neq 0$, and $\rho_1 = \rho.$

Since $\rho \Delta D$,

hence the abstract expression evaluation $\llbracket e \rrbracket^\# D \neq [0, 0]$, and $D_1 = D.$

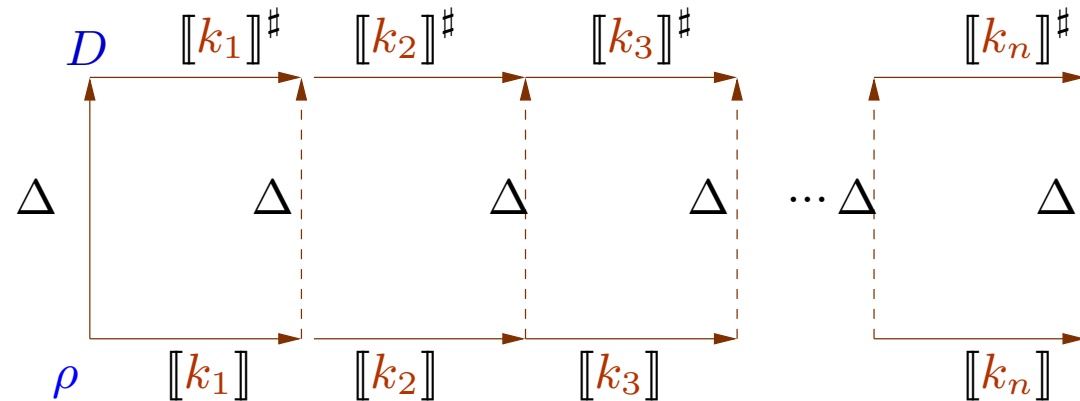
Recall, for a path $\pi = k_1 \dots k_n$,

$$[[\pi]] \rho = ([[k_n]] \circ \dots \circ [[k_1]]) \rho$$

$$[[\pi]]^\# D = ([[k_n]]^\# \circ \dots \circ [[k_1]]^\#) D$$

We conclude from above:

if $\rho \Delta D$ and $[[\pi]] \rho$ is defined then $[[\pi]] \rho \Delta [[\pi]]^\# D$.



Merge over All Paths (MOP):

$$\mathcal{D}^*[v] = \bigsqcup \{ \llbracket \pi \rrbracket^\# \top \mid \pi : start \rightarrow^* v \}$$

For any initial concrete state ρ and path $\pi : start \rightarrow^* v$, if $\llbracket \pi \rrbracket \rho$ is defined then

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Hence $\mathcal{D}^*[v]$ abstracts all states possible at node v .

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To compute it, we use the **constraint system** \mathcal{D}^* .

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How are the two related?

Merge over All Paths (MOP):

$$\mathcal{D}^*[v] = \bigsqcup \{ \llbracket \pi \rrbracket^\# D_0 \mid \pi : start \rightarrow^* v \}$$

Theorem:

Kam,Ullman 1975

Let \mathcal{D} be the smallest solution of the constraint system

$$\mathcal{D}[start] \supseteq D_0$$

$$\mathcal{D}[v] \supseteq \llbracket k \rrbracket^\# \mathcal{D}[u] \quad \text{for edge } k = (u, l, v)$$

Then we have

$$\mathcal{D}[v] \supseteq \mathcal{D}^*[v] \quad \text{for every } v$$

$$\text{In other words: } \mathcal{D}[v] \supseteq \llbracket \pi \rrbracket^\# D_0 \quad \text{for every } \pi : start \rightarrow^* v$$

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$$\llbracket \pi' \rrbracket^\# D_0 \sqsubseteq \mathcal{D}[u] \quad \text{induction hypothesis}$$

$$\llbracket \pi \rrbracket^\# D_0 = \llbracket k \rrbracket^\# (\llbracket \pi' \rrbracket^\# D_0)$$

$$\sqsubseteq \llbracket k \rrbracket^\# (\mathcal{D}[u]) \quad \text{monotonicity}$$

$$\sqsubseteq \mathcal{D}[v] \quad \mathcal{D} \text{ is a solution}$$

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Answer:

In general **yes**.

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Now let's assume that all the functions $[[k]]^\#$ are **distributive** ...

A function $f : \mathbb{D}_1 \rightarrow \mathbb{D}_2$ is called

- **distributive**, when $f(\bigsqcup X) = \bigsqcup\{f(x) \mid x \in X\}$ for all $\emptyset \neq X \subseteq \mathbb{D}_1$.
- **strict**, when $f(\perp) = \perp$.
- **total distributive**, when f is strict and distributive.

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$f(x) = x \cap A \cup B$ for some $A, B \subseteq U$.

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$$f(x \cup y) = (x \cup y) \cap A \cup B$$

Distributivity:

$$= (x \cap A) \cup (y \cap A) \cup B$$

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