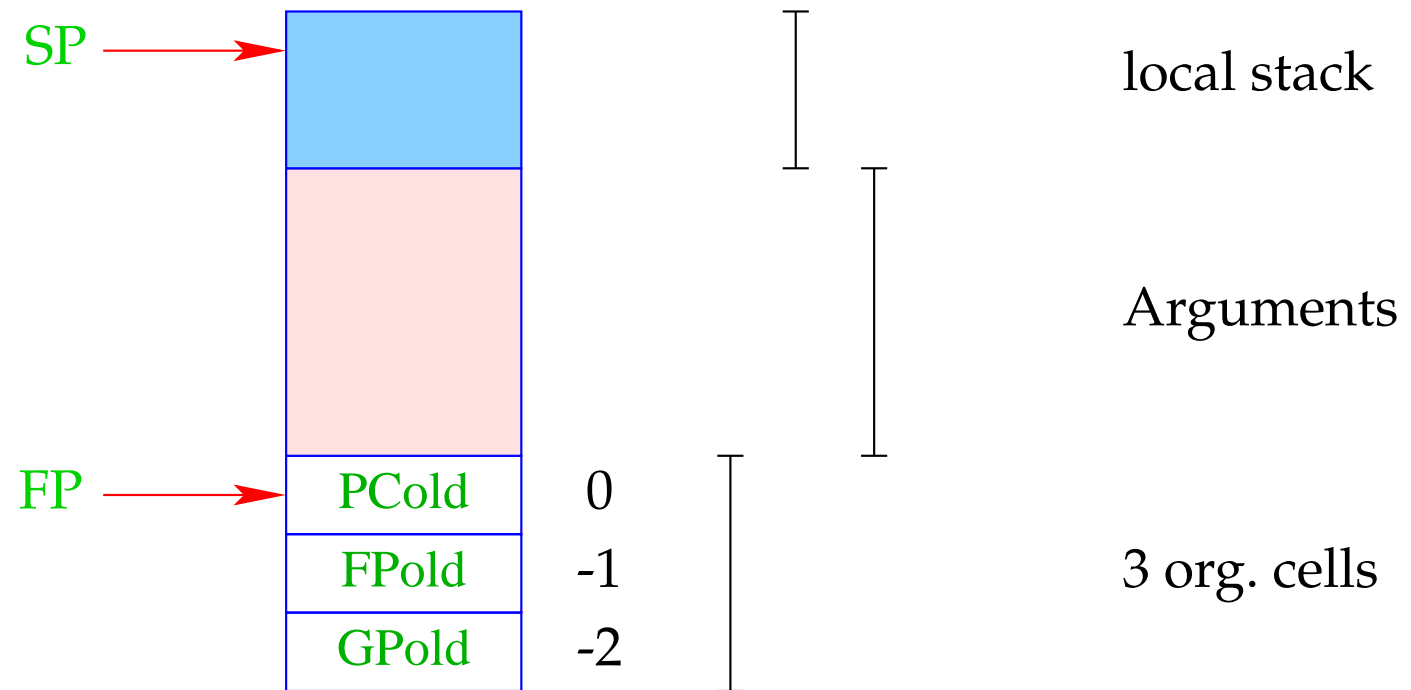
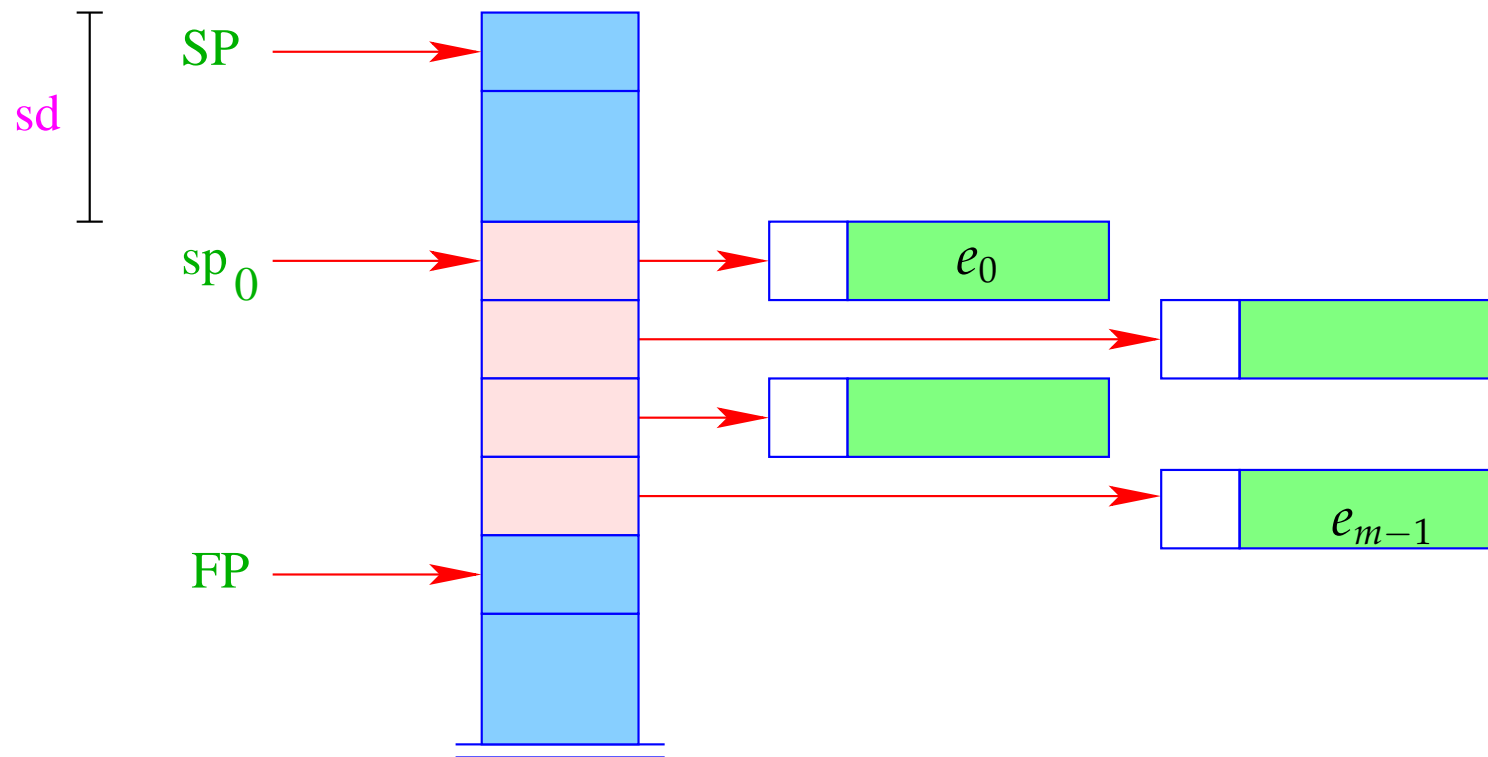


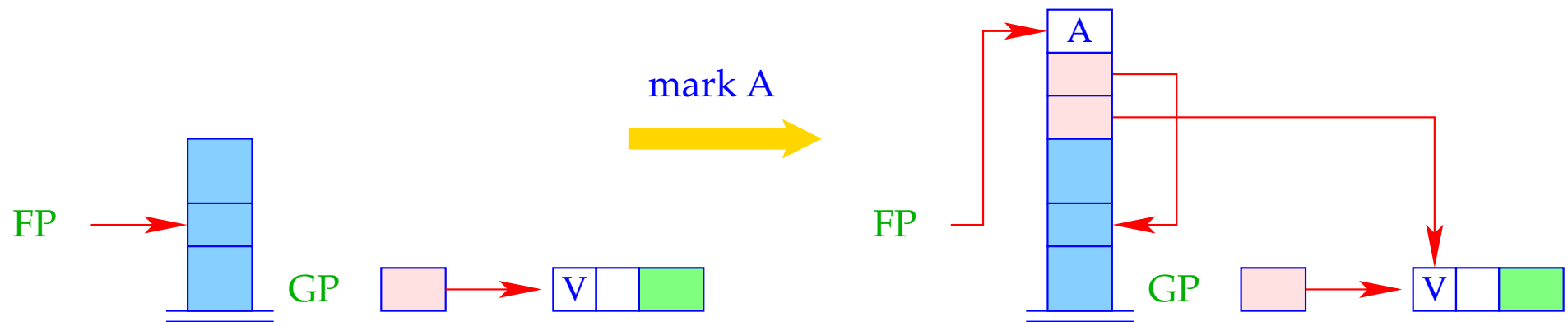
For the implementation of the new instruction, we must fix the organization of a stack frame:



Remember: Addressing of arguments and local variables

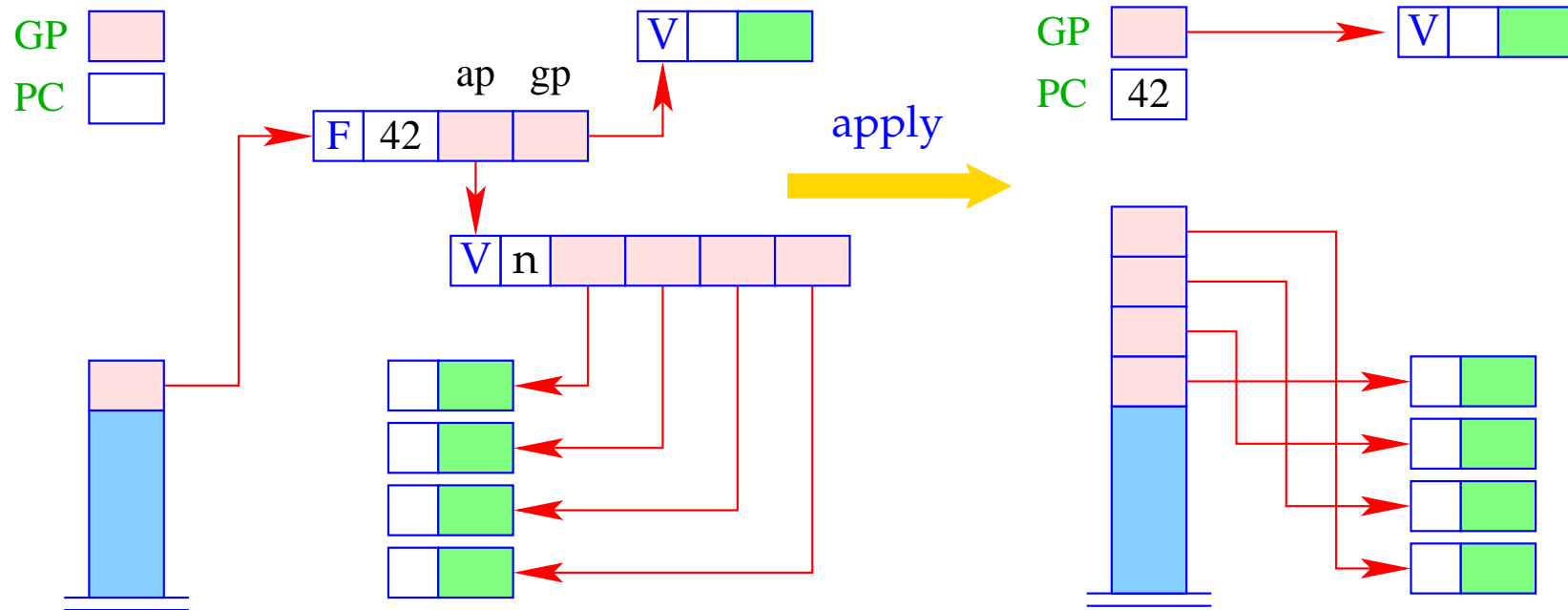


Different from the **CMa**, the instruction **mark A** already saves the return address:



$S[SP+1] = GP;$   
 $S[SP+2] = FP;$   
 $S[SP+3] = A;$   
 $FP = SP = SP + 3;$

The instruction `apply` unpacks the F-object, a reference to which (hopefully) resides on top of the stack, and continues execution at the address given there:



```

h = S[SP];
if (H[h] != (F,_,_))
    Error "no fun";
else {

```

```

    GP = h->gp; PC = h->cp;
    for (i=0; i < h->ap->n; i++)
        S[SP+i] = h->ap->v[i];
    SP = SP + h->ap->n - 1;
}

```

## Warning:

- The last element of the argument vector is the last to be put onto the stack. This must be the **first** argument reference.
- This should be kept in mind, when we treat the packing of arguments of an under-supplied function application into an F-object !!!

## 18 Over- and Undersupply of Arguments

The first instruction to be executed when entering a function body, i.e., after an `apply` is `targ k`.

This instruction checks whether there are enough arguments to evaluate the body.

Only if this is the case, the execution of the code for the body is started.

Otherwise, i.e. in the case of `under-supply`, a new F-object is returned.

The test for number of arguments uses:  $SP - FP$

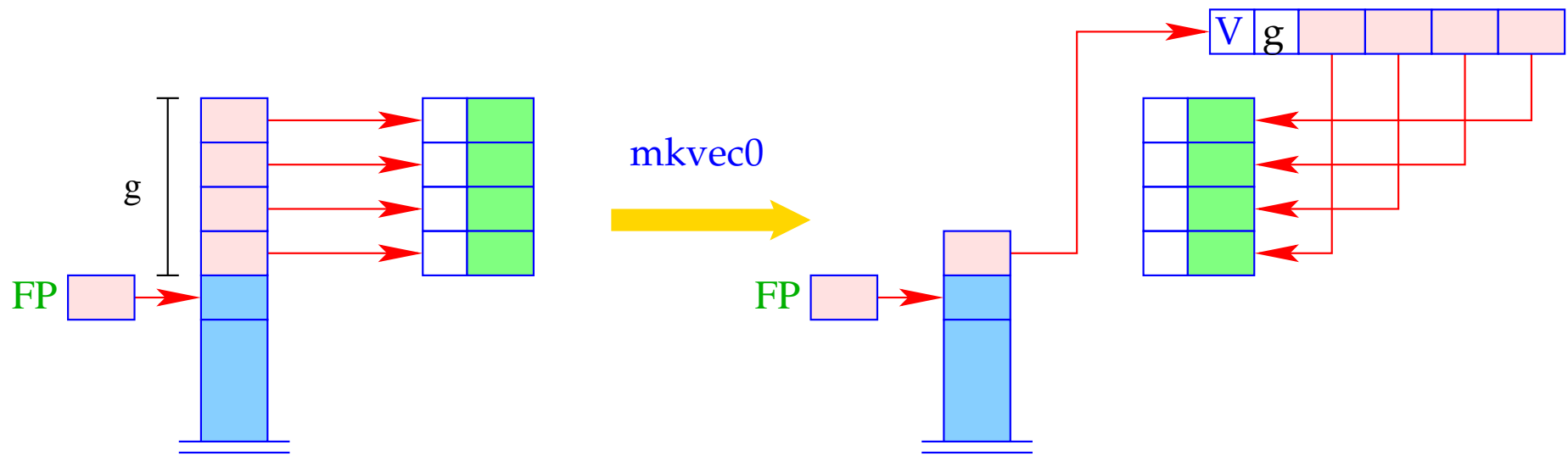
`targ k` is a complex instruction.

We decompose its execution in the case of `under-supply` into several steps:

```
targ k = if (SP - FP < k) {  
    mkvec0;           // creating the argumentvector  
    wrap;            // wrapping into an F - object  
    popenv;         // popping the stack frame  
}
```

The combination of these steps into one instruction is a kind of optimization :-)

The instruction `mkvec0` takes all references from the stack above `FP` and stores them into a vector:



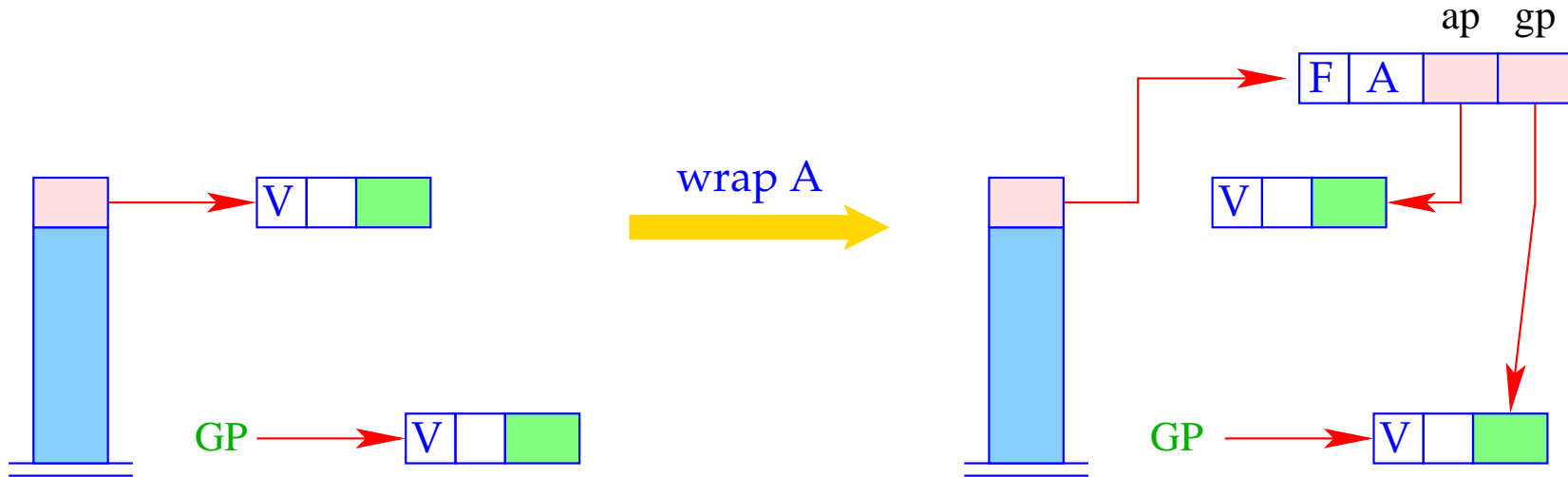
```

g = SP-FP; h = new (V, g);
SP = FP+1;
for (i=0; i<g; i++)
    h->v[i] = S[SP + i];
S[SP] = h;

```

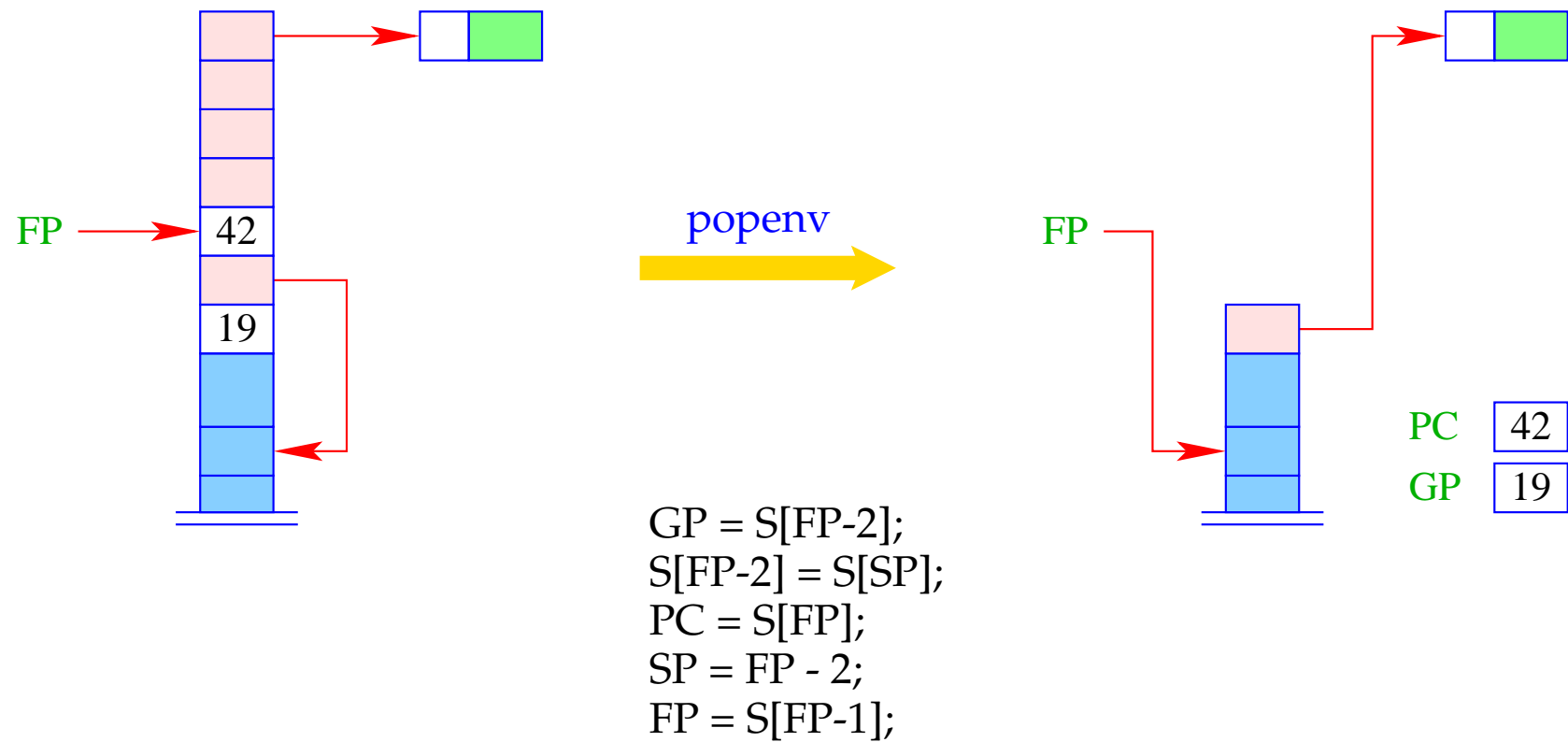


The instruction `wrap A` wraps the argument vector together with the global vector into an F-object:

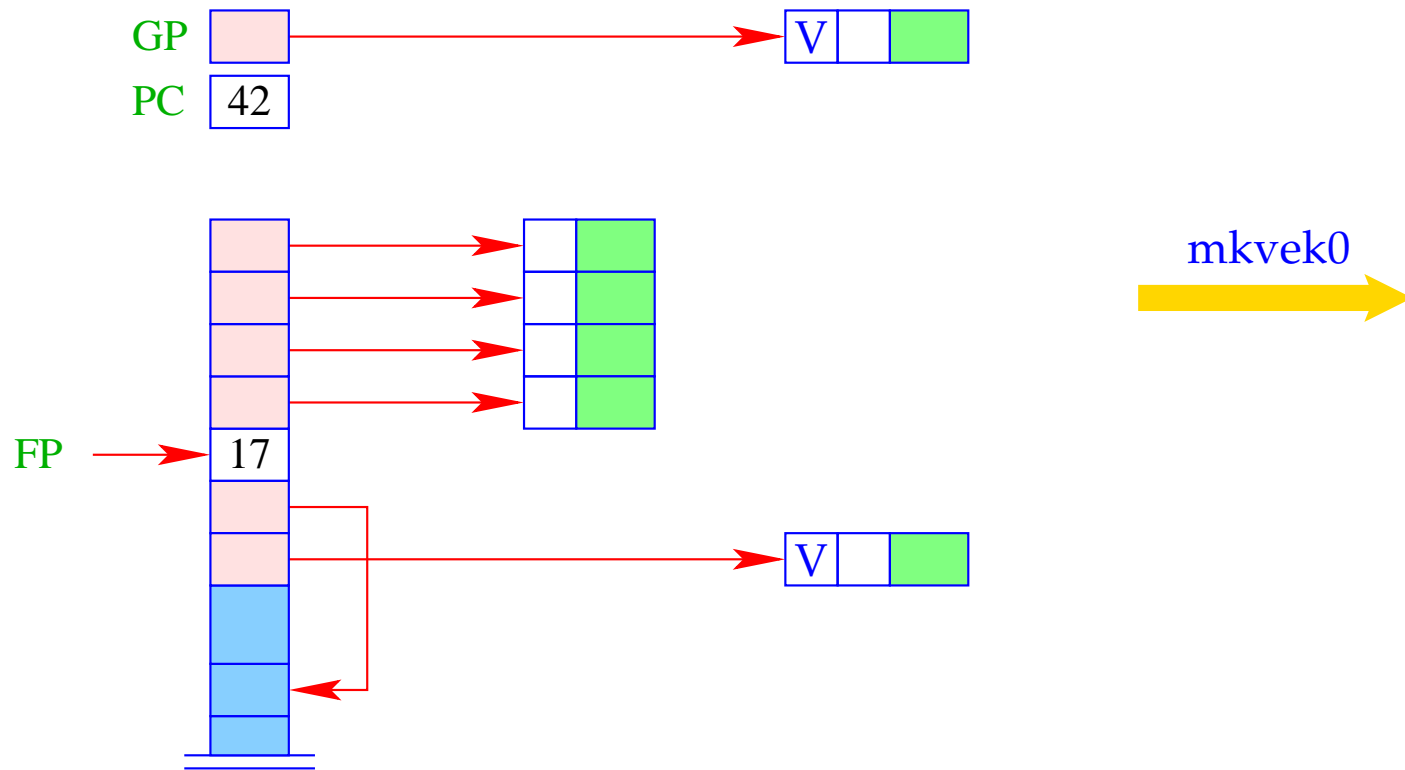


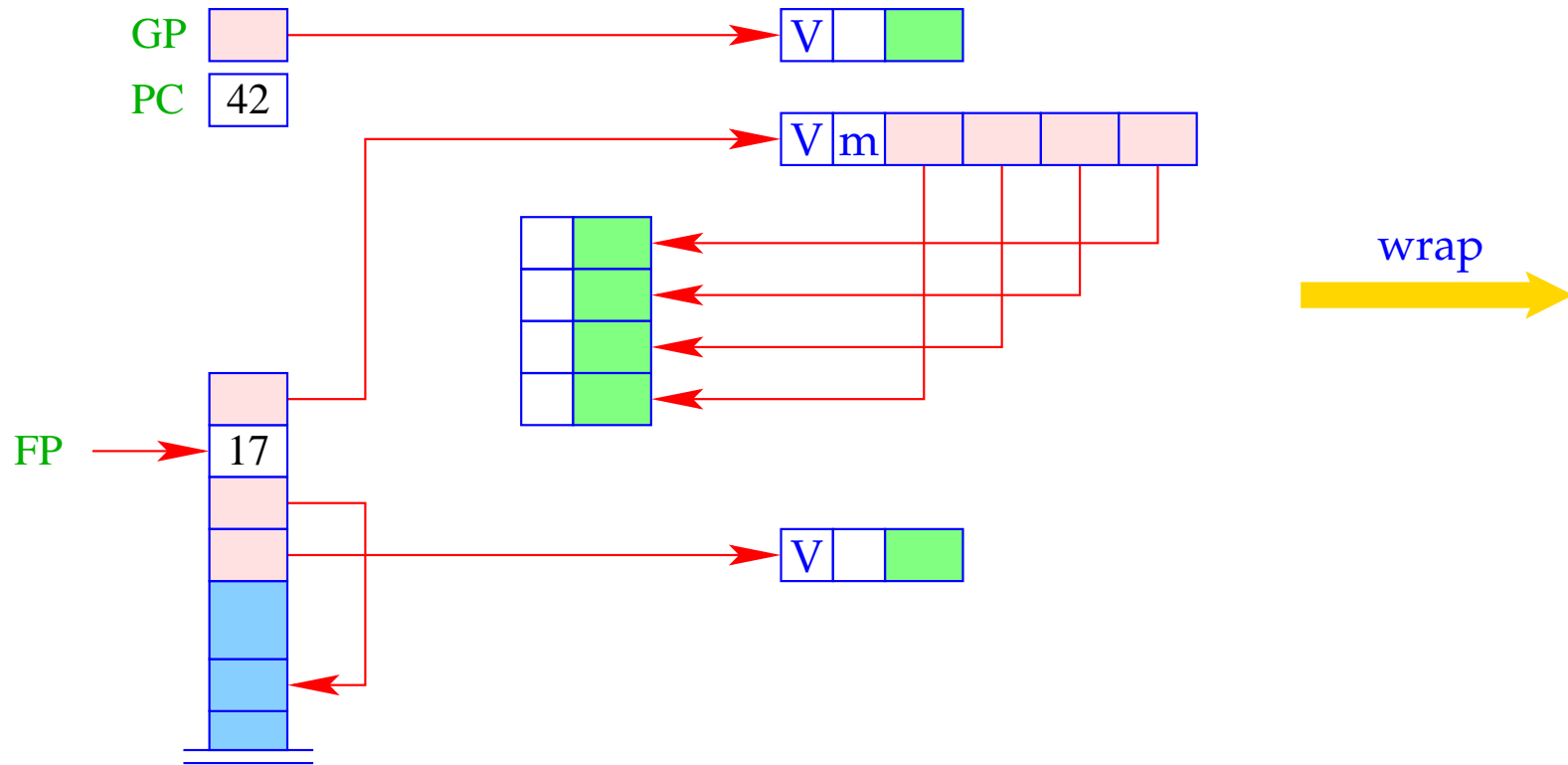
$S[SP] = \text{new } (F, A, S[SP], GP);$

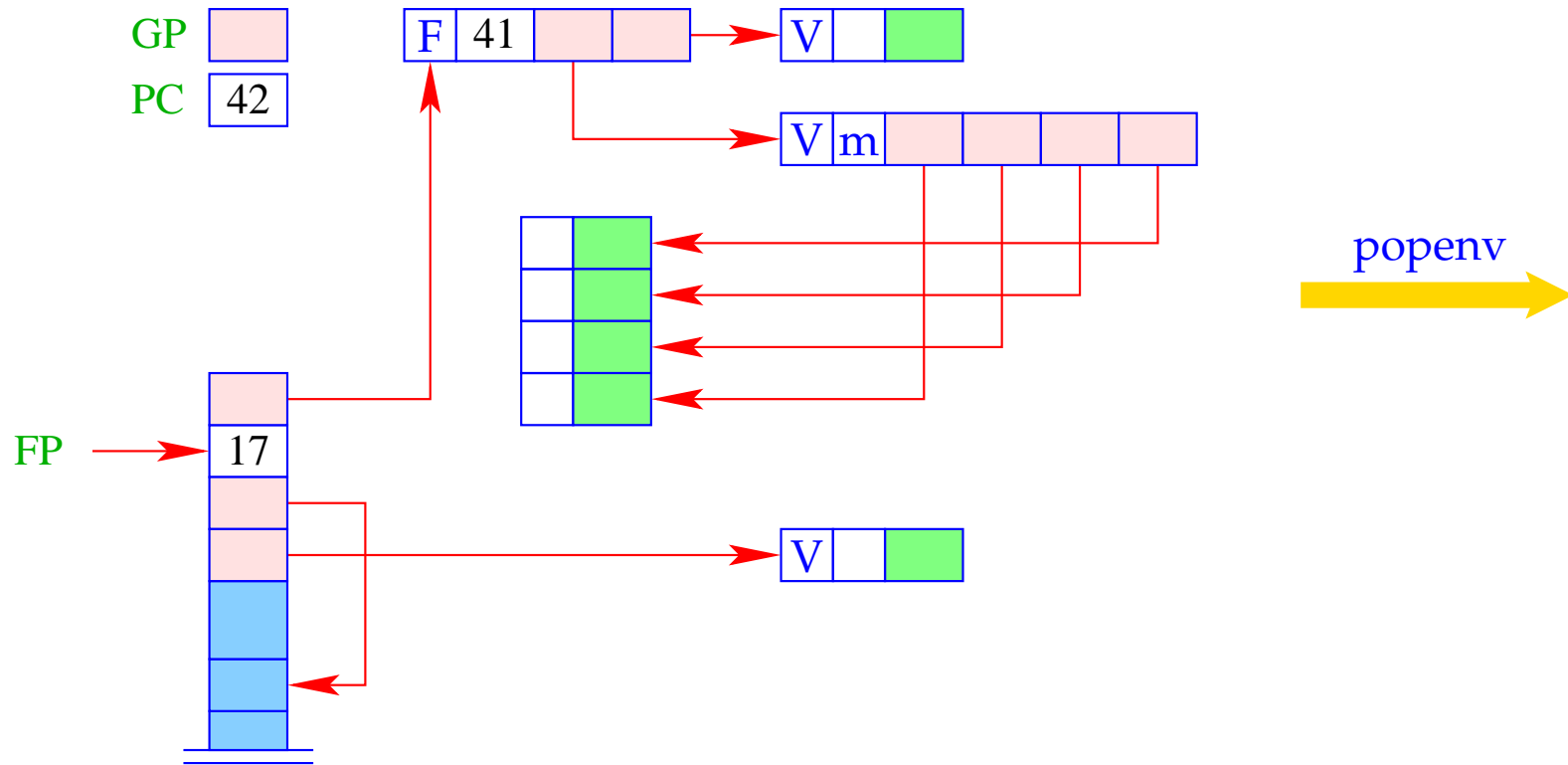
The instruction `popenv` finally releases the stack frame:

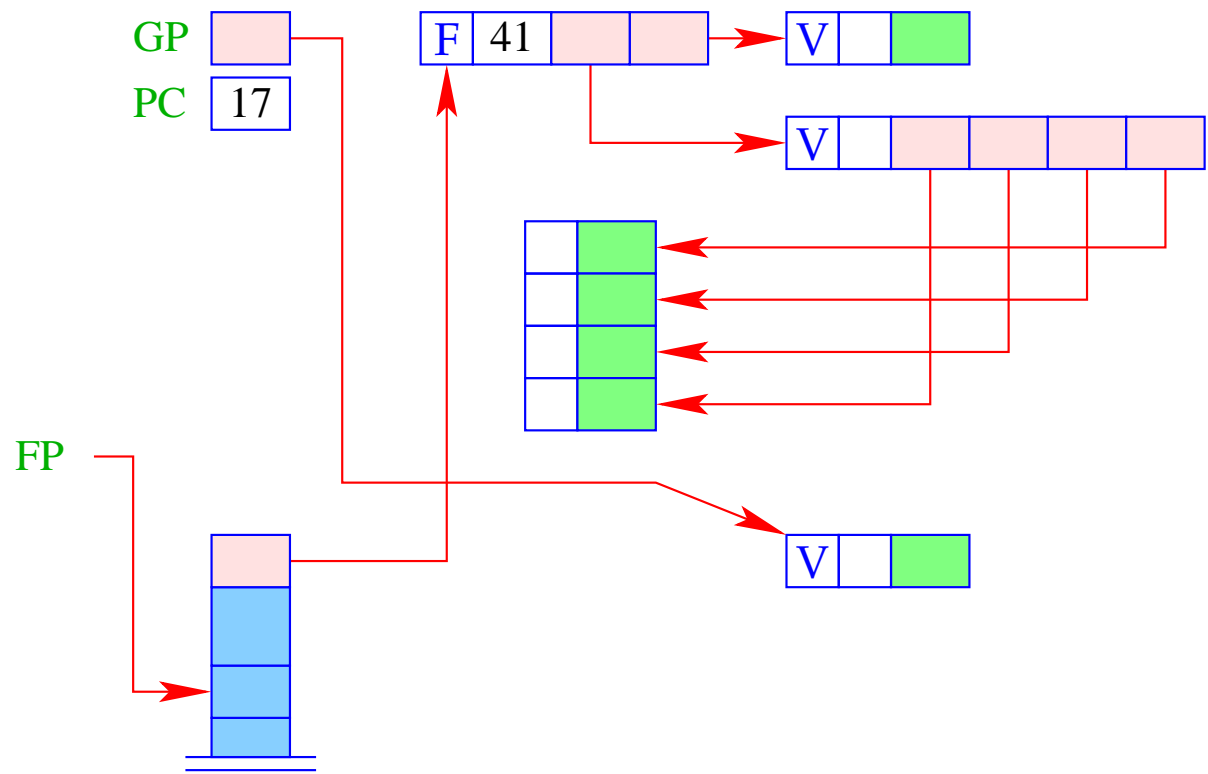


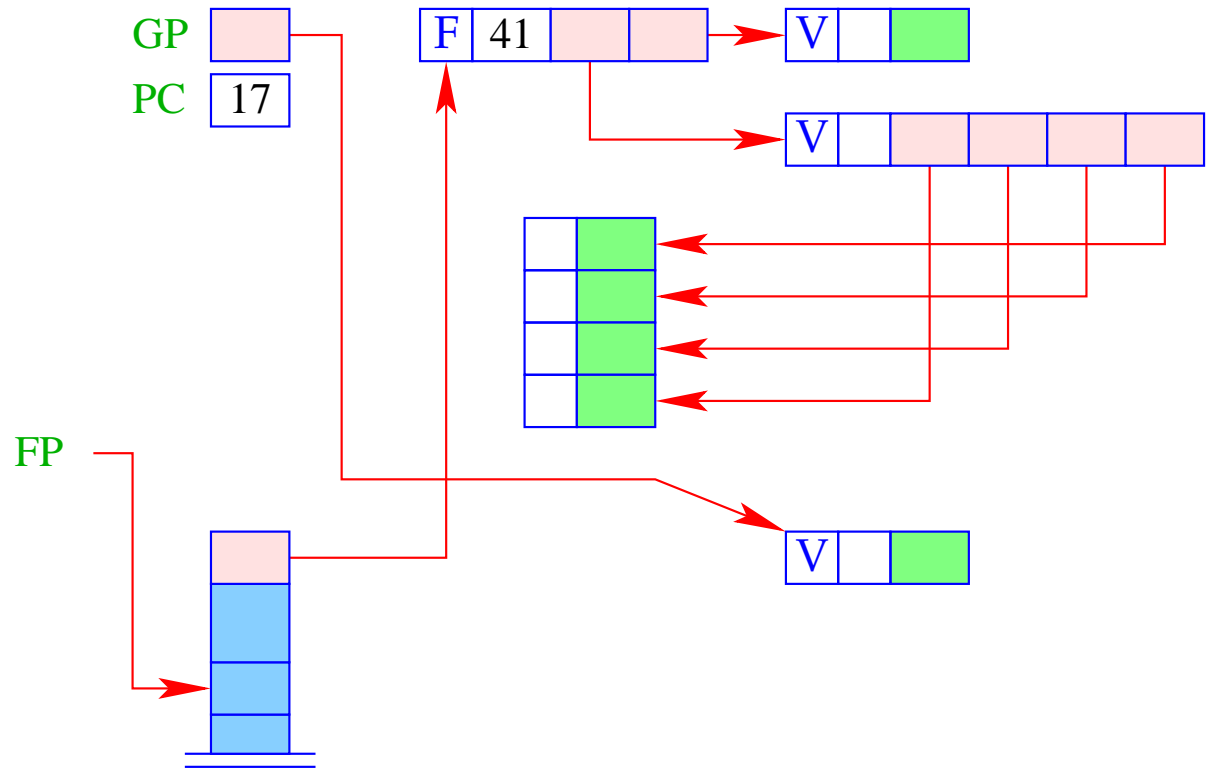
Thus, we obtain for `targ k` in the case of under supply:











- The stack frame can be released **after the execution of the body** if exactly the right number of arguments was available.
- If there is an **oversupply** of arguments, the body must evaluate to a function, which consumes the rest of the arguments ...
- The check for this is done by **return k**:

```

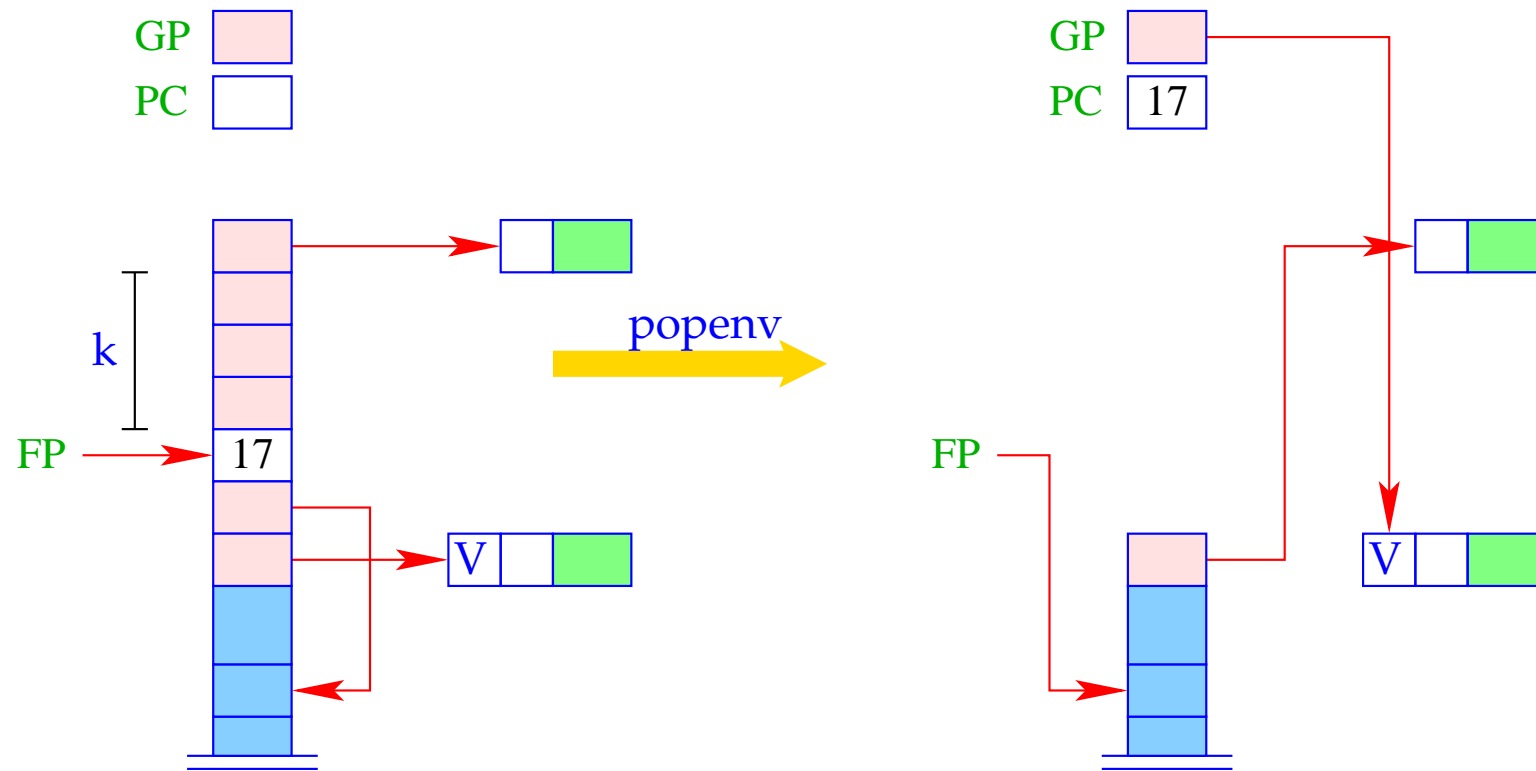
return k = if (SP - FP = k + 1)
    popenv;           // Done
else {                // There are more arguments
    slide k;
    apply;           // another application
}

```

The execution of **return k** results in:



Case: Done



Case: Over-supply

