

19 letrec-Expressions

Consider the expression $e \equiv \mathbf{letrec} \ y_1 = e_1; \dots; y_n = e_n \ \mathbf{in} \ e_0$.

The translation of e must deliver an instruction sequence that

- allocates local variables y_1, \dots, y_n ;
- in the case of
 - CBV**: evaluates e_1, \dots, e_n and binds the y_i to their values;
 - CBN**: constructs closures for the e_1, \dots, e_n and binds the y_i to them;
- evaluates the expression e_0 and returns its value.

Warning:

In a **letrec**-expression, the definitions can use variables that will be allocated only **later!** \implies **Dummy**-values are put onto the stack before processing the definition.

For **CBN**, we obtain:

```
codeV e ρ sd = alloc n           // allocates local variables
                codeC e1 ρ' (sd + n)
                rewrite n
                ...
                codeC en ρ' (sd + n)
                rewrite 1
                codeV e0 ρ' (sd + n)
                slide n           // deallocates local variables
```

where $\rho' = \rho \oplus \{y_i \mapsto (L, \text{sd} + i) \mid i = 1, \dots, n\}$.

In the case of **CBV**, we also use `codeV` for the expressions e_1, \dots, e_n .

Warning:

Recursive definitions of basic values are **undefined** with **CBV!!!**

Example:

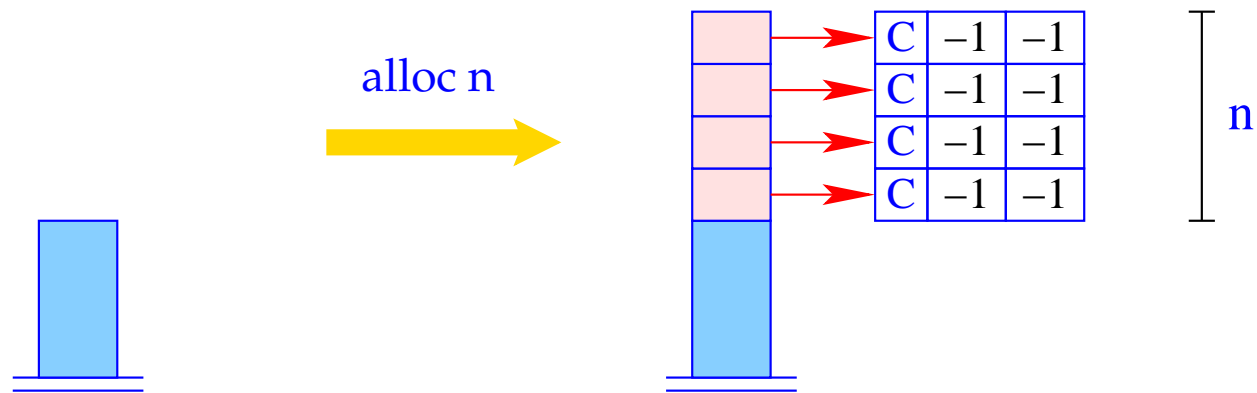
Consider the expression

$$e \equiv \mathbf{letrec} \ f = \mathbf{fn}x, y \Rightarrow \mathbf{if}y \leq 1 \ \mathbf{then} \ x \ \mathbf{else} \ f(x * y)(y - 1) \ \mathbf{in} \ f1$$

for $\rho = \emptyset$ and $\mathbf{sd} = 0$. We obtain (for **CBV**):

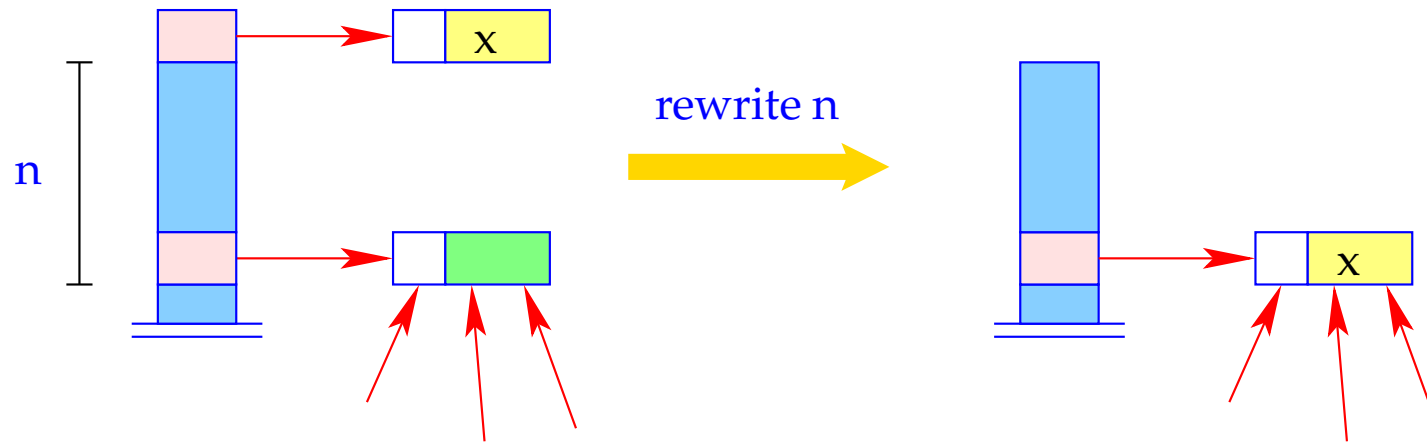
0	alloc 1	0	A:	targ 2	4	loadc 1
1	pushloc 0	0		...	5	mkbasic
2	mkvec 1	1		return 2	5	pushloc 4
2	mkfunval A	2	B:	rewrite 1	6	apply
2	jump B	1		mark C	2	C: slide 1

The instruction `alloc n` reserves n cells on the stack and initialises them with n dummy nodes:



```
for (i=1; i<=n; i++)  
    S[SP+i] = new (C,-1,-1);  
SP = SP + n;
```

The instruction `rewrite n` overwrites the contents of the heap cell pointed to by the reference at $S[SP-n]$:



$H[S[SP-n]] = H[S[SP]];$
 $SP = SP - 1;$

- The `reference` $S[SP - n]$ remains unchanged!
- Only its `contents` is changed!

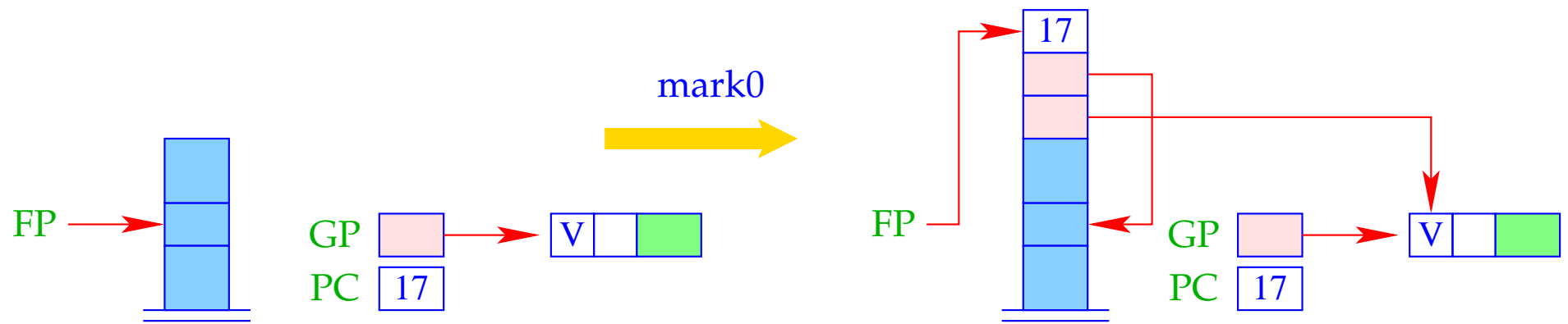
20 Closures and their Evaluation

- Closures are needed only for the implementation of CBN.
- Before the value of a variable is accessed (with CBN), this value **must** be available.
- Otherwise, a stack frame must be created to determine this value.
- This task is performed by the instruction `eval`.

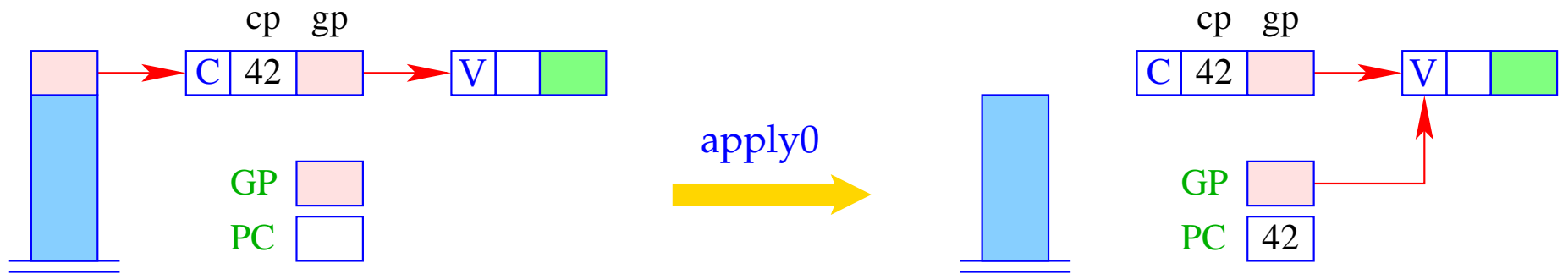
`eval` can be decomposed into small actions:

```
eval = if (H[S[SP]] ≡ (C, -, -)) {  
    mark0;           // allocation of the stack frame  
    pushloc 3;      // copying of the reference  
    apply0;         // corresponds to apply  
}
```

- A closure can be understood as a parameterless function. Thus, there is no need for an `ap`-component.
- Evaluation of the closure thus means evaluation of an application of this function to 0 arguments.
- In contrast to `mark A`, `mark0` dumps the current `PC`.
- The difference between `apply` and `apply0` is that no argument vector is put on the stack.

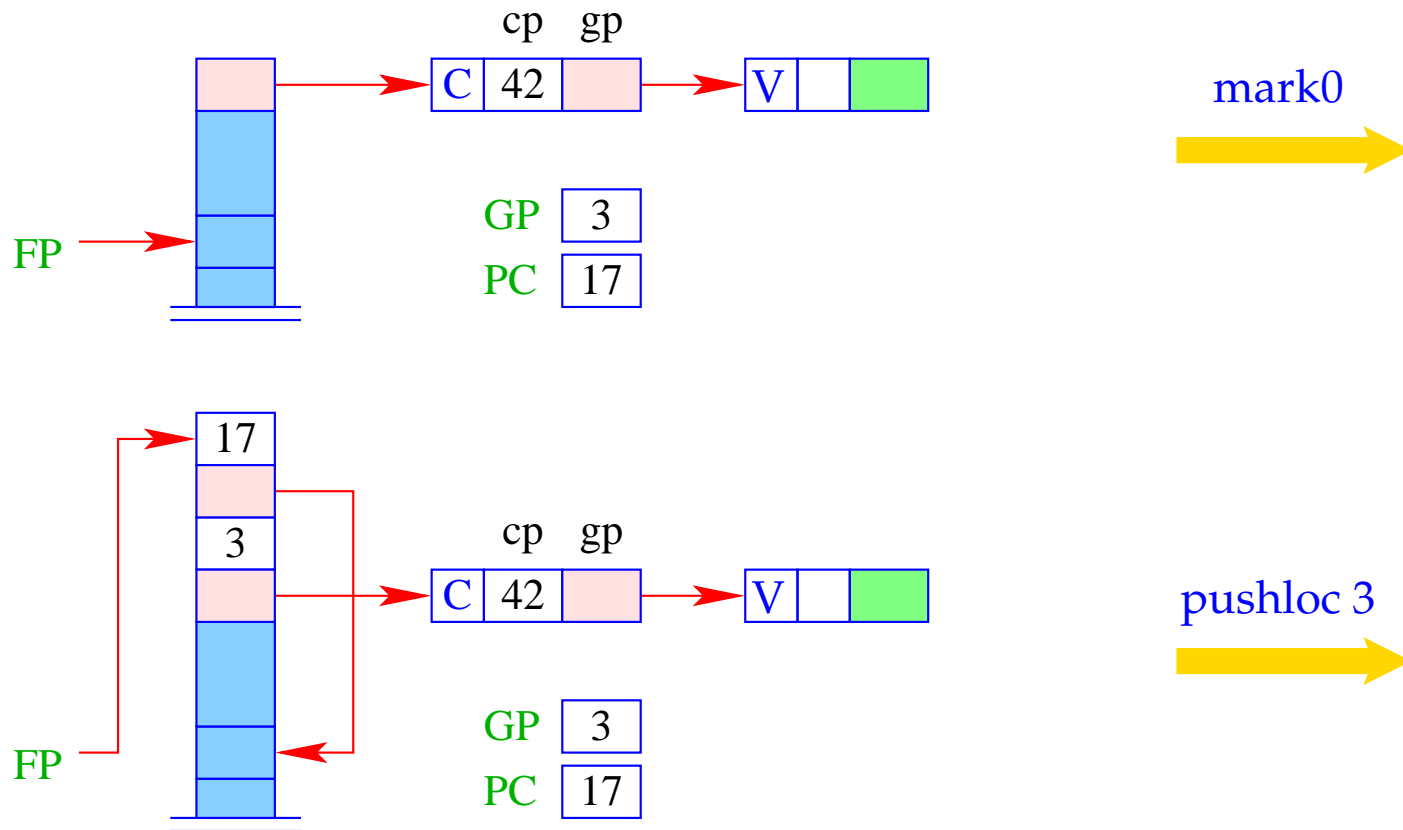


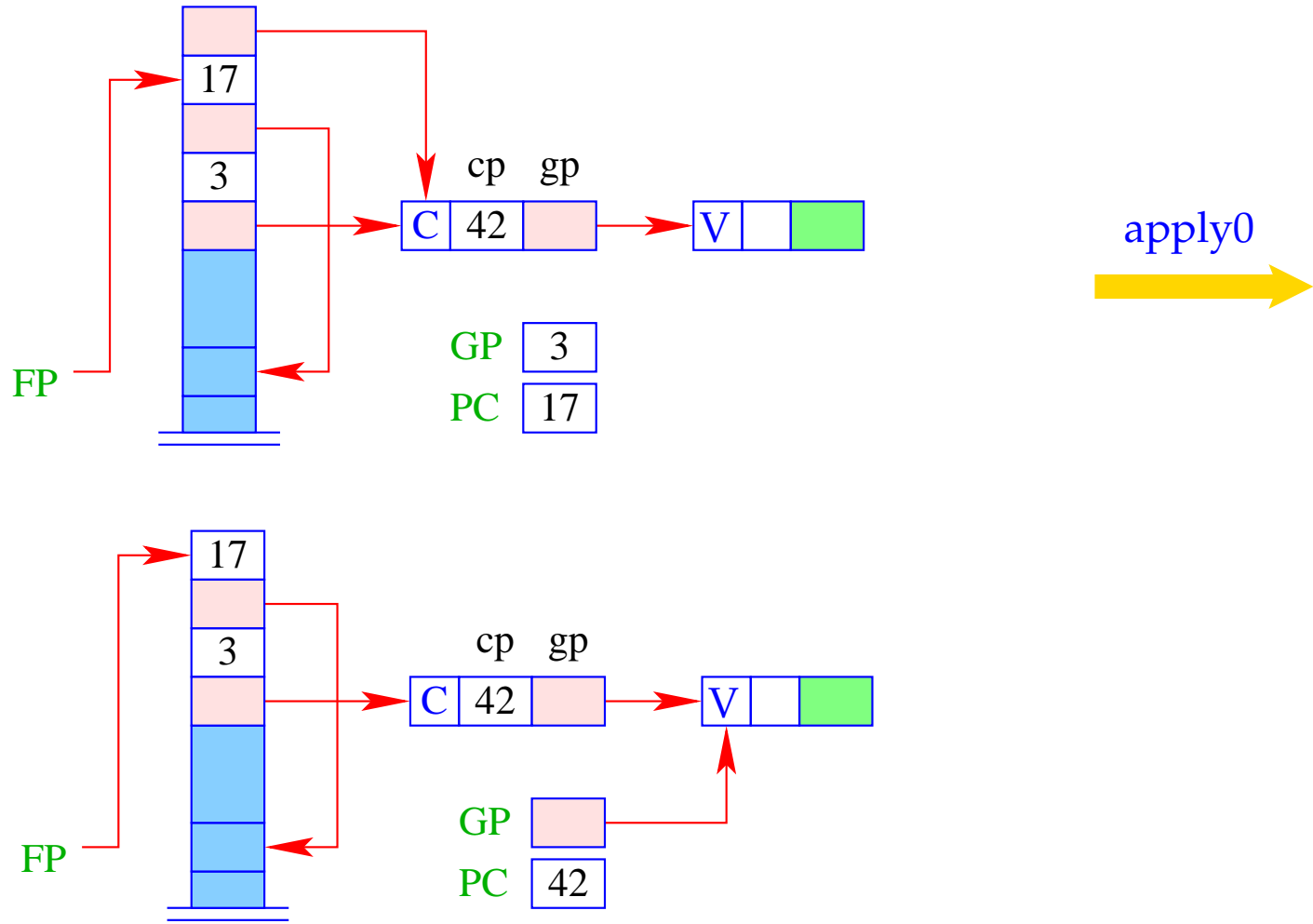
$S[SP+1] = GP;$
 $S[SP+2] = FP;$
 $S[SP+3] = PC;$
 $FP = SP = SP + 3;$



$h = S[SP]; SP--;$
 $GP = h \rightarrow gp; PC = h \rightarrow cp;$

We thus obtain for the instruction `eval`:





The **construction** of a closure for an expression e consists of:

- Packing the bindings for the free variables into a vector;
- Creation of a C-object, which contains a reference to this vector and to the code for the evaluation of e :

```

codeC e ρ sd =      getvar z0 ρ sd
                     getvar z1 ρ (sd + 1)
                     ...
                     getvar zg-1 ρ (sd + g - 1)
                     mkvec g
                     mkclos A
                     jump B
A : codeV e ρ' 0
    update
B : ...

```

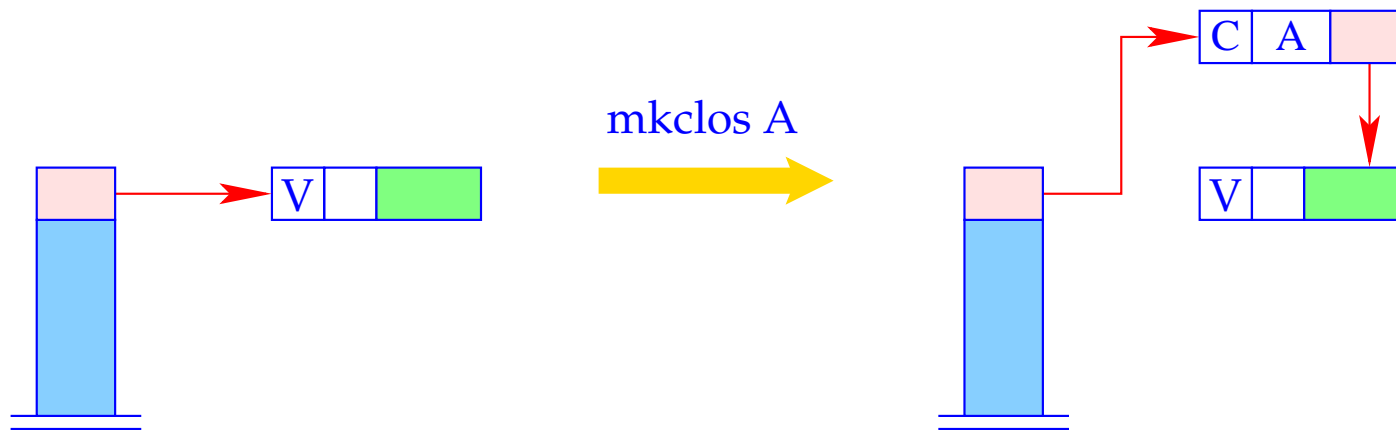
where $\{z_0, \dots, z_{g-1}\} = \text{free}(e)$ and $\rho' = \{z_i \mapsto (G, i) \mid i = 0, \dots, g - 1\}$.

Example:

Consider $e \equiv a * a$ with $\rho = \{a \mapsto (L, 0)\}$ and $sd = 1$. We obtain:

1	pushloc 1	0	A:	pushglob 0	2	getbasic
2	mkvec 1	1		eval	2	mul
2	mkcloc A	1		getbasic	1	mkbasic
2	jump B	1		pushglob 0	1	update
		2		eval	2	B: ...

- The instruction `mkclos A` is analogous to the instruction `mkfunval A`.
- It generates a C-object, where the included code pointer is `A`.

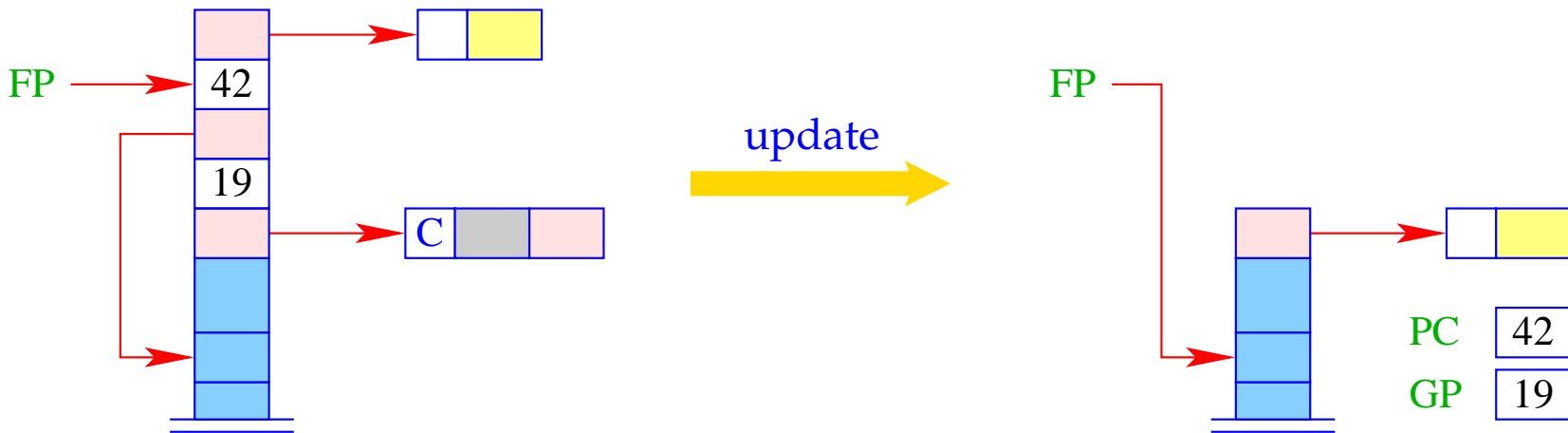


`S[SP] = new (C, A, S[SP]);`

In fact, the instruction `update` is the combination of the two actions:

`popenv`
`rewrite 1`

It overwrites the closure with the computed value.



21 Optimizations I: Global Variables

Observation:

- Functional programs construct many F- and C-objects.
- This requires the inclusion of (the bindings of) all global variables.
Recall, e.g., the construction of a closure for an expression e ...


```

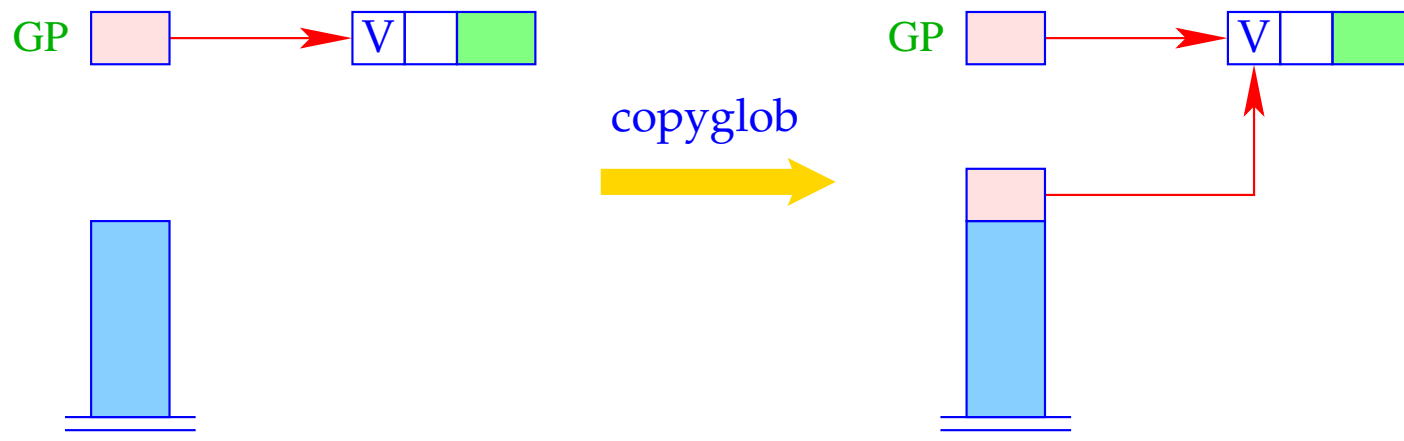
codeC e ρ sd =   getvar z0 ρ sd
                   getvar z1 ρ (sd + 1)
                   ...
                   getvar zg-1 ρ (sd + g - 1)
                   mkvec g
                   mkclos A
                   jump B
A : codeV e ρ' 0
    update
B : ...

```

where $\{z_0, \dots, z_{g-1}\} = \text{free}(e)$ and $\rho' = \{z_i \mapsto (G, i) \mid i = 0, \dots, g-1\}$.

Idea:

- **Reuse** Global Vectors, i.e. share Global Vectors!
- Profitable in the translation of **let**-expressions or function applications: Build one Global Vector for the union of the free-variable sets of all let-definitions resp. all arguments.
- Allocate (references to) global vectors with multiple uses in the stack frame like local variables!
- Support the access to the current **GP** by an instruction `copyglob` :



copyglob

```
SP++;  
S[SP] = GP;
```

- The optimization will cause Global Vectors to contain **more** components than just references to the free the variables that occur in one expression ...

Disadvantage: Superfluous components in Global Vectors prevent the deallocation of already useless heap objects \implies **Space Leaks :-)**

Potential Remedy: Deletion of references at the end of their life time.

22 Optimizations II: Closures

In some cases, the construction of closures can be avoided, namely for

- Basic values,
- Variables,
- Functions.

Basic Values:

The construction of a closure for the value is at least as expensive as the construction of the B-object itself!

Therefore:

$$\text{code}_C b \rho sd = \text{code}_V b \rho sd = \begin{array}{l} \text{loadc b} \\ \text{mkbasic} \end{array}$$

This replaces:

mkvec 0		jump B	mkbasic	B:	...
mkclos A	A:	loadc b	update		

Variables:

Variables are either bound to values or to C-objects. Constructing another closure is therefore superfluous. Therefore:

$$\text{code}_C x \rho sd = \text{getvar } x \rho sd$$

This replaces:

<code>getvar</code> $x \rho sd$	<code>mkclos</code> A	A:	<code>pushglob</code> 0	<code>update</code>
<code>mkvec</code> 1	<code>jump</code> B		<code>eval</code>	B: ...

Example:

$e \equiv \text{letrec } a = b; b = 7 \text{ in } a.$ `codeV` $e \emptyset 0$ produces:

0	<code>alloc</code> 2	3	<code>rewrite</code> 2	3	<code>mkbasic</code>	2	<code>pushloc</code> 1
2	<code>pushloc</code> 0	2	<code>loadc</code> 7	3	<code>rewrite</code> 1	3	<code>eval</code>
						3	<code>slide</code> 2

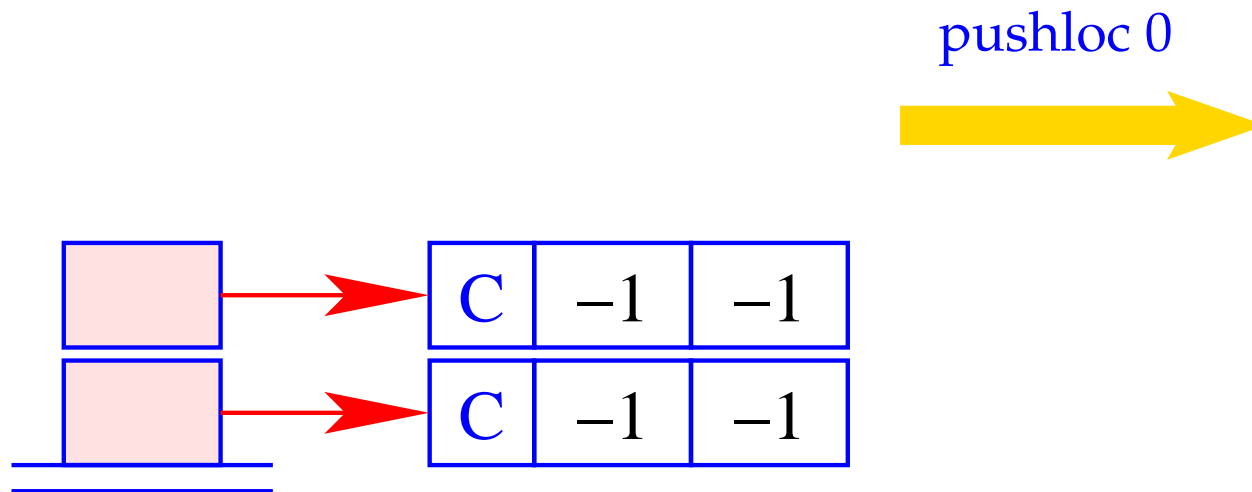
The execution of this instruction sequence should deliver the basic value 7 ...

0	alloc 2	3	rewrite 2	3	mkbasic	2	pushloc 1
2	pushloc 0	2	loadc 7	3	rewrite 1	3	eval
						3	slide 2

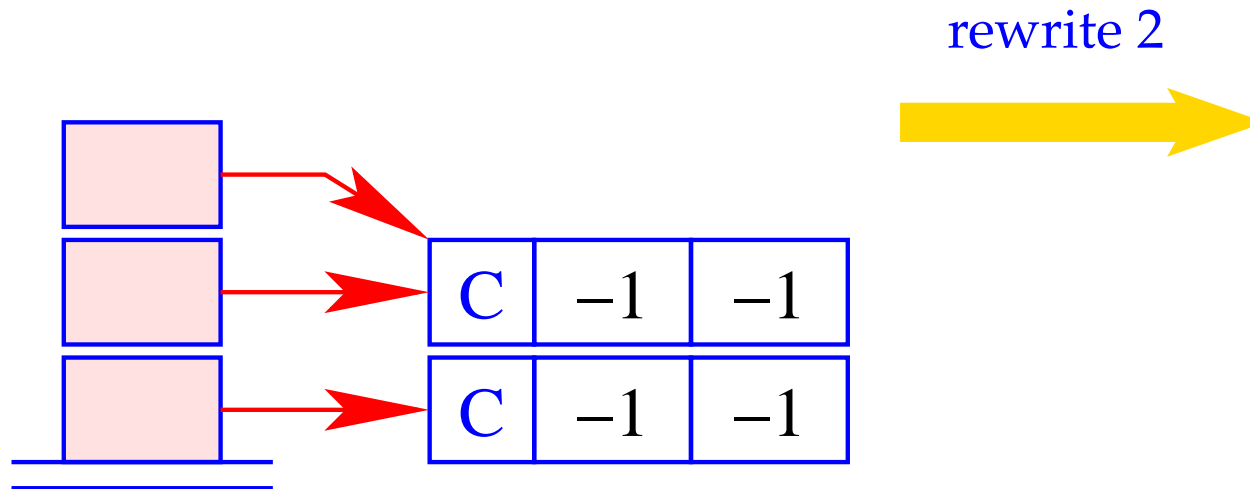
alloc 2



0	alloc 2	3	rewrite 2	3	mkbasic	2	pushloc 1
2	pushloc 0	2	loadc 7	3	rewrite 1	3	eval
						3	slide 2



0	alloc 2	3	rewrite 2	3	mkbasic	2	pushloc 1
2	pushloc 0	2	loadc 7	3	rewrite 1	3	eval
						3	slide 2



0 alloc 2

2 pushloc 0

3 rewrite 2

2 loadc 7

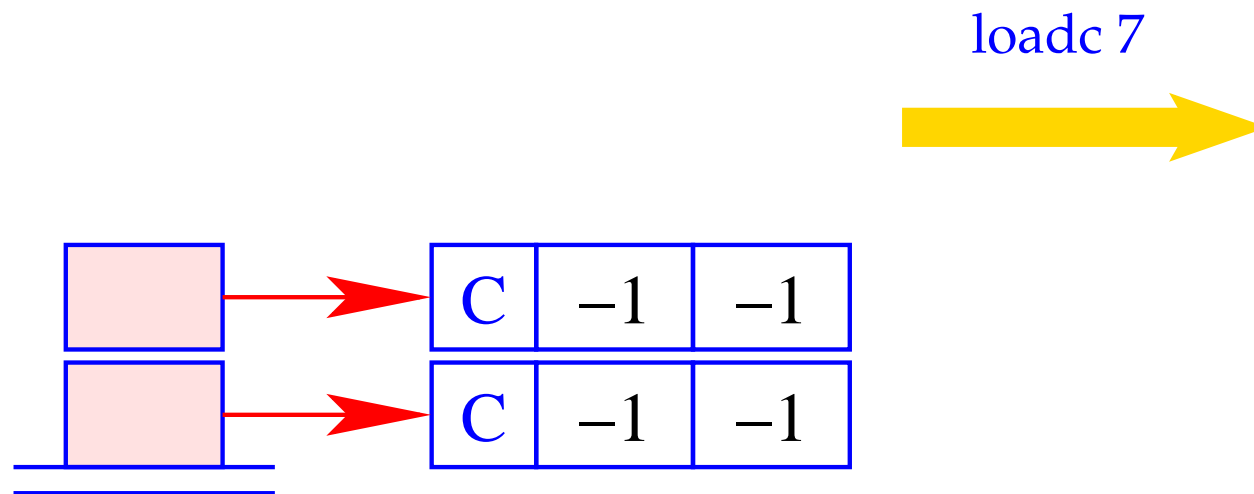
3 mkbasic

3 rewrite 1

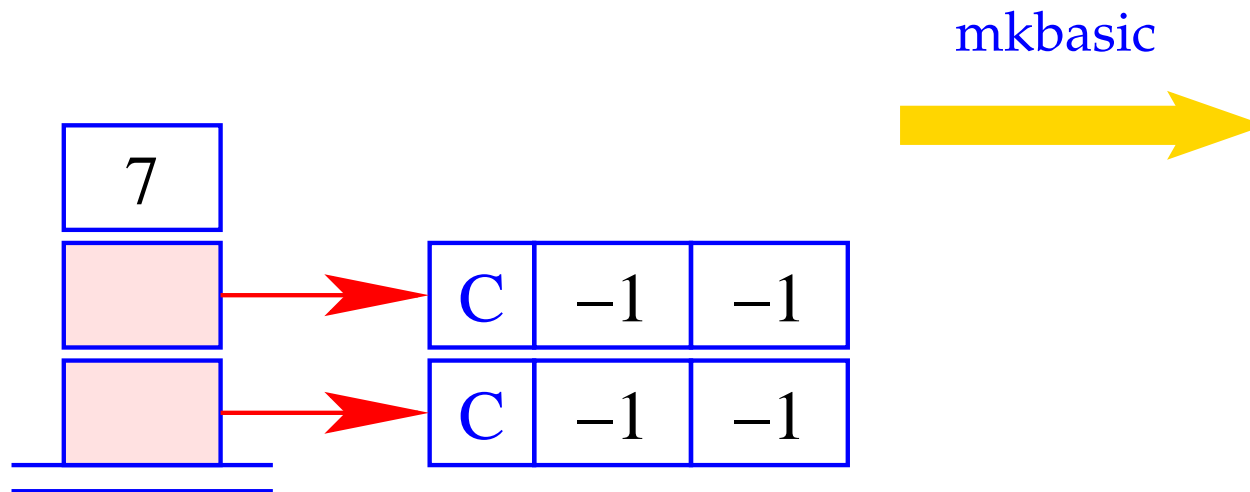
2 pushloc 1

3 eval

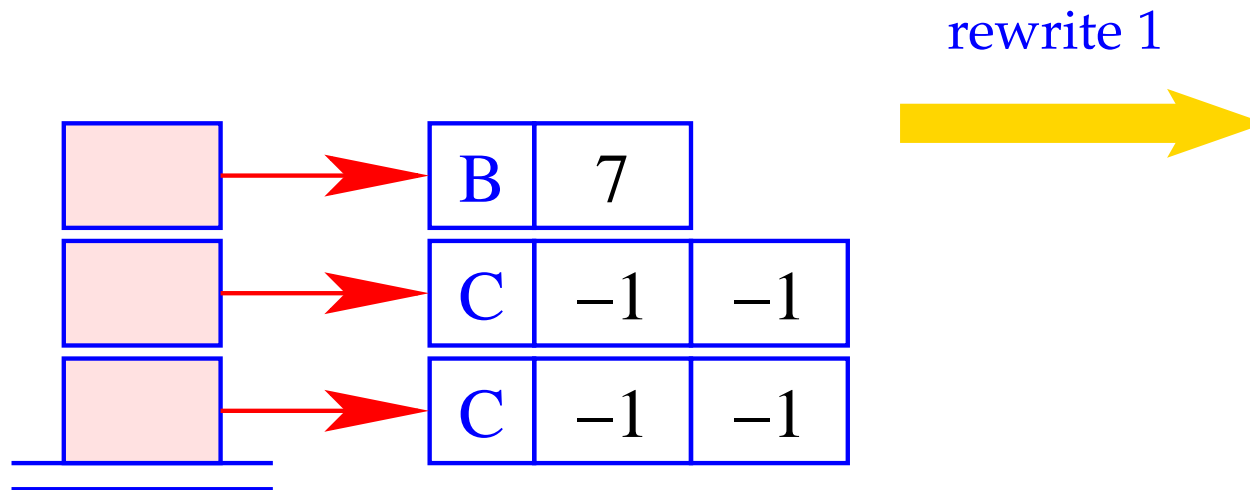
3 slide 2



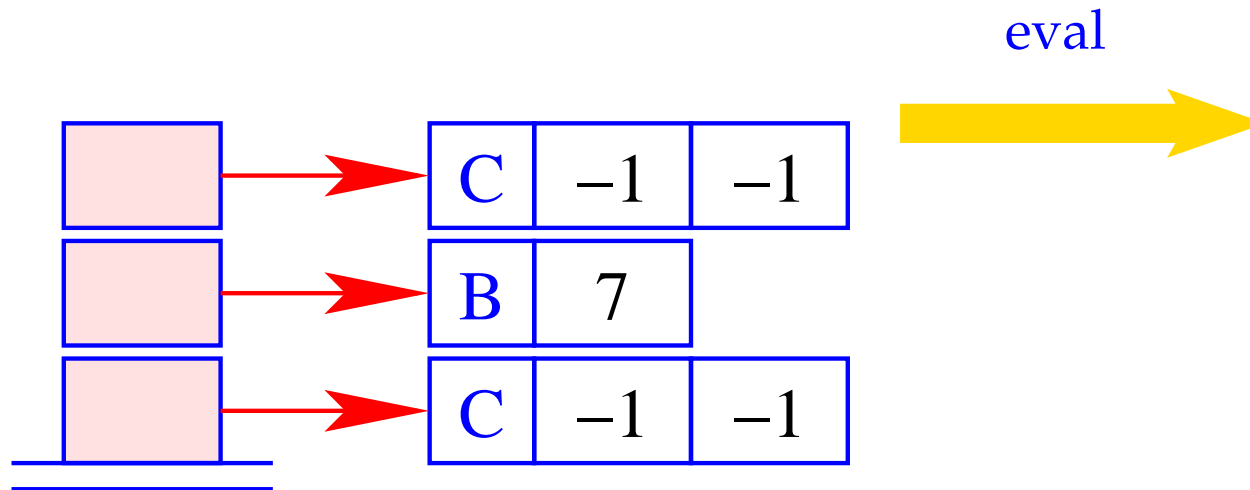
0	alloc 2	3	rewrite 2	3	mkbasic	2	pushloc 1
2	pushloc 0	2	loadc 7	3	rewrite 1	3	eval
						3	slide 2



0	alloc 2	3	rewrite 2	3	mkbasic	2	pushloc 1
2	pushloc 0	2	loadc 7	3	rewrite 1	3	eval
						3	slide 2



0	alloc 2	3	rewrite 2	3	mkbasic	2	pushloc 1
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0	alloc 2	3	rewrite 2	3	mkbasic	2	pushloc 1
2	pushloc 0	2	loadc 7	3	rewrite 1	3	eval
						3	slide 2

Segmentation Fault !!

Apparently, this optimization was not quite **correct** :-)

The Problem:

Binding of variable y to variable x **before** x 's dummy node is replaced!!



The Solution:

cyclic definitions: reject sequences of definitions like

let $a = b; \dots b = a$ **in** \dots

acyclic definitions: order the definitions $y = x$ such that the dummy node for the right side of x is already overwritten.

Functions:

Functions are values, which are not evaluated further. Instead of generating code that constructs a closure for an F-object, we generate code that constructs the F-object directly.

Therefore:

$$\text{code}_C (\text{fn } x_0, \dots, x_{k-1} \Rightarrow e) \rho \text{sd} = \text{code}_V (\text{fn } x_0, \dots, x_{k-1} \Rightarrow e) \rho \text{sd}$$

23 The Translation of a Program Expression

Execution of a program e starts with

$$PC = 0 \quad SP = FP = GP = -1$$

The expression e must not contain **free variables**.

The value of e should be determined and then a **halt** instruction should be executed.

$$\text{code } e = \text{code}_V e \ \emptyset \ 0 \\ \text{halt}$$

Remarks:

- The code schemata as defined so far produce **Spaghetti code**.
- Reason: Code for function bodies and closures placed directly behind the instructions **mkfunval** resp. **mkclos** with a jump over this code.
- Alternative: Place this code somewhere else, e.g. **following** the **halt**-instruction:

Advantage: Elimination of the direct jumps following **mkfunval** and **mkclos**.

Disadvantage: The code schemata are more complex as they would have to accumulate the code pieces in a **Code-Dump**.



Solution:

Disentangle the Spaghetti code in a subsequent optimization phase :-)

Example: **let** $a = 17$; $f = \mathbf{fn}$ $b \Rightarrow a + b$ **in** f 42

Disentanglement of the jumps produces:

0	loadc 17	2	mark B	3	B:	slide 2	1	pushloc 1
1	mkbasic	5	loadc 42	1		halt	2	eval
1	pushloc 0	6	mkbasic	0	A:	targ 1	2	getbasic
2	mkvec 1	6	pushloc 4	0		pushglob 0	2	add
2	mkfunval A	7	eval	1		eval	1	mkbasic
		7	apply	1		getbasic	1	return 1