

## Existence of least solutions: Knaster-Tarski

**Fact:** In a complete lattice  $\mathbb{D}$ , every monotone function  $f : \mathbb{D} \rightarrow \mathbb{D}$  has a **least fixpoint**  $a$ .

**Fixpoint:** an element  $x$  such that  $f(x) = x$ .

**Prefixpoint:** an element  $x$  such that  $f(x) \sqsubseteq x$ .

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**Prefixpoint:** an element  $x$  such that  $f(x) \sqsubseteq x$ .

Let  $P = \{x \in \mathbb{D} \mid f(x) \sqsubseteq x\}$  (the set of prefixpoints).

The least fixpoint of  $f$  is  $a = \bigsqcap P$ .

(1)  $a \in P$ :

$$f(a) \sqsubseteq f(d) \sqsubseteq d \text{ for all } d \in P.$$

$$\implies f(a) \text{ is a lower bound of } P.$$

$$\implies f(a) \sqsubseteq a.$$

$\implies$   $a$  is the least prefixpoint.

(2)  $f(a) = a$ :

$f(a) \sqsubseteq a$ , from (1)

$\implies f^2(a) \sqsubseteq f(a)$ , by monotonicity

$\implies f(a) \in P$

$\implies a \sqsubseteq f(a)$

Hence  $a$  is the least prefixpoint and is also a fixpoint.

Hence  $a$  is also the least fixpoint.

**Example 1:** Consider partial order  $\mathbb{D}_1 = \mathbb{N}$  with  $0 \sqsubseteq 1 \sqsubseteq 2 \sqsubseteq \dots$

The function  $f(x) = x+1$  is monotonic.

However it has no fixpoint.

Actually  $\mathbb{D}_1$  is not a complete lattice.

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**Example 2:** Now we consider  $\mathbb{D}_2 = \mathbb{N} \cup \{\infty\}$ .

This is a complete lattice.

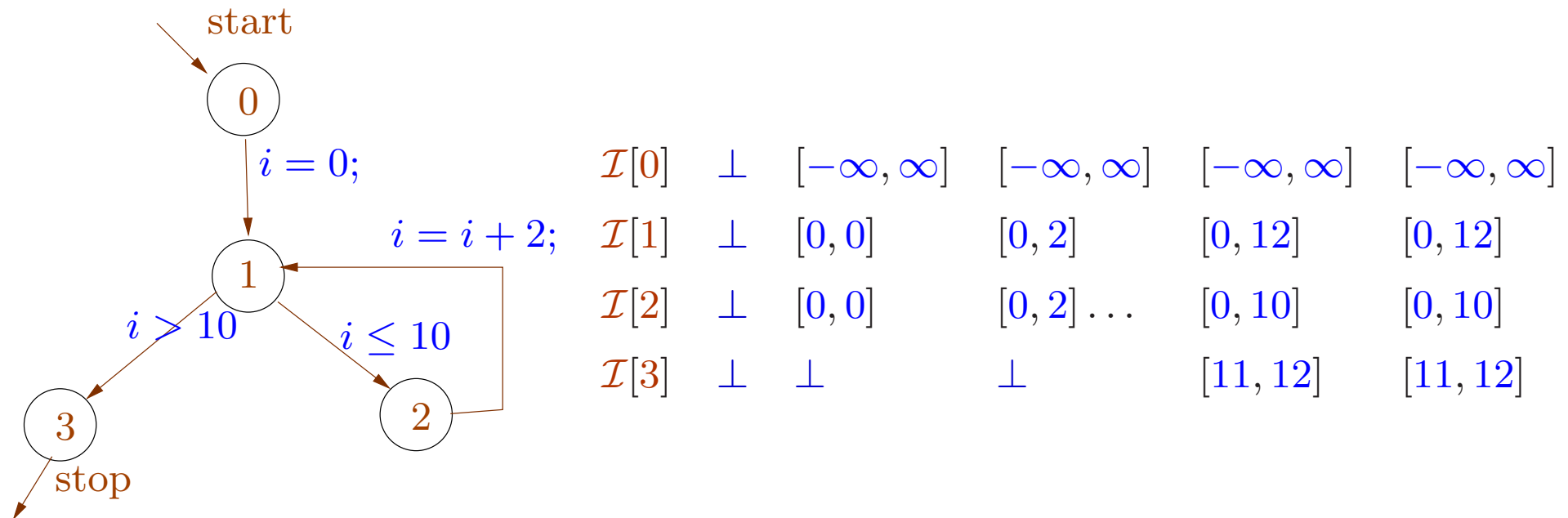
The function  $f(x) = x+1$  is again monotonic.

The only fixpoint is  $\infty$ :  $\infty+1 = \infty$ .

# Abstract Interpretation: Cousot, Cousot 1977

We use a suitable complete lattice as the domain of abstract values.

Example: **intervals** as abstract values:



The analysis **guarantees** e.g. that at node **1** the value of  $i$  is always in the interval  $[0, 12]$ .

We have the set of concrete states  $\mathcal{S} = (\text{Vars} \rightarrow \mathbb{Z})$ .

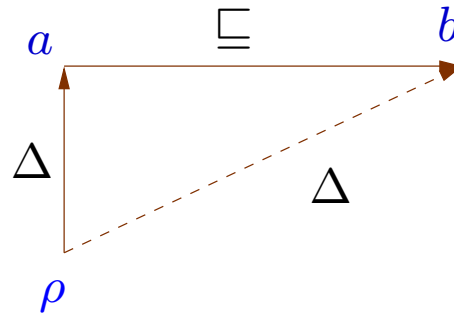
We choose a complete lattice  $\mathbb{D}$  of abstract states.

We define an abstraction relation

$$\Delta : \mathcal{S} \times \mathbb{D}$$

with the condition that

$$\rho \Delta a \wedge a \sqsubseteq b \implies \rho \Delta b$$



The concretization function:  $\gamma(a) = \{\rho \mid \rho \Delta a\}$ .

**Example:** For a program on two integer variables,  $\text{Vars} = \{x, y\}$ .

The concrete states are from the set  $\mathcal{S} = (\text{Vars} \rightarrow \mathbb{Z})$  (or equivalently  $\mathbb{Z}^2$ ).

For **interval analysis**, we choose the **complete lattice**

$$\mathbb{D}_{\mathbb{I}} = (\text{Vars} \rightarrow \mathbb{I})_{\perp} = (\text{Vars} \rightarrow \mathbb{I}) \cup \{\perp\}$$

where  $\mathbb{I} = \{[l, u] \mid l \in \mathbb{Z} \cup \{-\infty\}, u \in \mathbb{Z} \cup \{\infty\}, l \leq u\}$  is the set of intervals.



Partial order on  $\mathbb{I}$ :  $[l_1, u_1] \sqsubseteq [l_2, u_2]$  iff  $l_1 \geq l_2$  and  $u_1 \leq u_2$

(As usual,  $-\infty \leq n \leq \infty$  for all  $n \in \mathbb{Z}$ .)

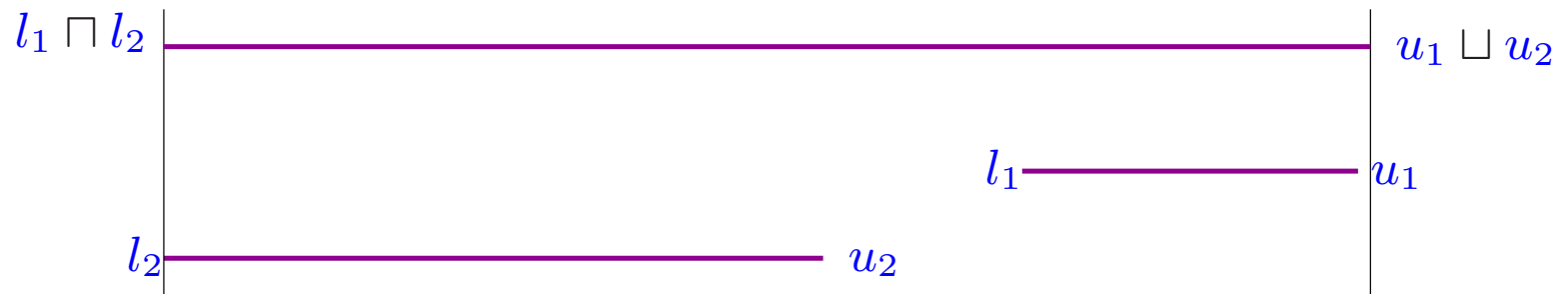


Partial order on  $\mathbf{Vars} \rightarrow \mathbb{I}$ :  $D_1 \sqsubseteq D_2$  iff  $D_1(x) \sqsubseteq D_2(x)$ .

Extension to  $(\mathbf{Vars} \rightarrow \mathbb{I})_{\perp}$ :  $\perp \sqsubseteq D$  for all  $D$ .

$(\mathbf{Vars} \rightarrow \mathbb{I})_{\perp}$  is a complete lattice.  $(\mathbf{Vars} \rightarrow \mathbb{I})$  is not.

In particular we define  $[l_1, u_1] \sqcup [l_2, u_2] = [l_1 \sqcap l_2, u_1 \sqcup u_2]$ .



$\perp$  represents the “unreachable state”: maps every variable to the “empty interval”.

The abstraction relation:

$$\rho \Delta D \quad \text{iff} \quad D \neq \perp \quad \text{and} \quad \rho(x) \Delta D(x) \quad \text{for each } x.$$

where  $n \Delta [l, u]$  iff  $l \leq n \leq u$ .

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where  $n \Delta [l, u]$  iff  $l \leq n \leq u$ .

This satisfies the required condition:

Suppose  $\rho \Delta D_1$  and  $D_1 \sqsubseteq D_2$ .

$\implies D_1 \neq \perp$  and  $D_2 \neq \perp$ .

$\rho(x) \Delta D_1(x)$  and  $D_1(x) \sqsubseteq D_2(x)$  for each  $x$ .

$\implies \rho(x) \Delta D_1(x)$  for each  $x$ .



The concretization function:

$$\gamma(\perp) = \{\}$$

$$\gamma(D) = \{\rho \mid \rho(x) \Delta D(x)\}, \quad \text{for } D \neq \perp$$

$$\begin{aligned} \gamma(\{x \mapsto [3, 5], y \mapsto [0, 7]\}) = & \quad \{\{x \mapsto 3, y \mapsto 0\}, \{x \mapsto 3, y \mapsto 1\}, \\ & \quad \dots \{x \mapsto 3, y \mapsto 7\} \\ & \quad \dots \{x \mapsto 5, y \mapsto 0\} \dots \{x \mapsto 5, y \mapsto 7\}\} \end{aligned}$$

Abstraction of the partial transformation induced by edges.

Recall the edges  $k = (u, l, v)$  induce a partial transformation on concrete states:

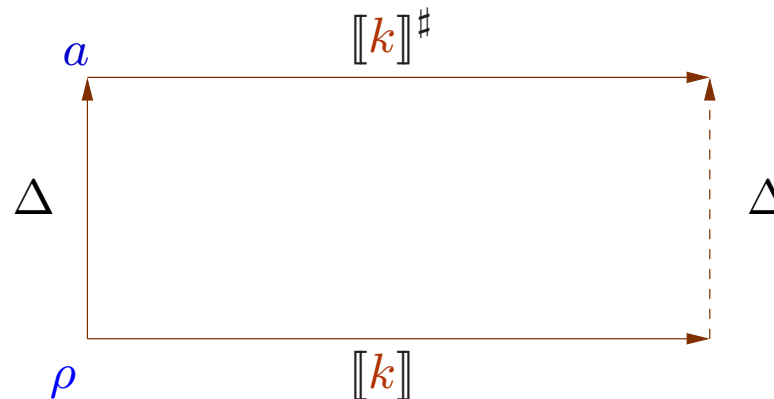
$$\llbracket k \rrbracket = \llbracket l \rrbracket : \mathcal{S} \rightarrow \mathcal{S}$$

Now on our chosen domain  $\mathbb{D}$  we define a monotonic abstract transformation:

$$\llbracket k \rrbracket^\# = \llbracket l \rrbracket^\# : \mathbb{D} \rightarrow \mathbb{D}$$

The abstract transformation should simulate the concrete transformation:

if  $\rho \Delta a$  and  $\llbracket l \rrbracket \rho$  is defined then  $\llbracket l \rrbracket \rho \Delta \llbracket l \rrbracket^\# a$ .



## Abstract transformation for interval analysis.

For concrete operators  $\square$  we define **monotonic** abstract operators  $\square^\#$  such that

$$x_1 \Delta a_1 \wedge \dots \wedge x_n \Delta a_n \implies \square(x_1, \dots, x_n) \Delta \square^\#(a_1, \dots, a_n)$$

addition:

$$\begin{aligned} [l_1, u_1] +^\# [l_2, u_2] &= [l_1 + l_2, u_1 + u_2]. \\ - + \infty &= \infty \\ - + -\infty &= \infty \\ // \infty + -\infty &\text{ is undefined.} \end{aligned}$$

subtraction:

$$-^\# [l, u] = [-u, -l]$$

Multiplication:  $[l_1, u_1] \ast^\# [l_2, u_2] = [m, n]$  where

$$m = l_1 l_2 \sqcap l_1 u_2 \sqcap u_1 l_2 \sqcap u_1 u_2$$

$$n = l_1 l_2 \sqcup l_1 u_2 \sqcup u_1 l_2 \sqcup u_1 u_2$$

Example:

$$[1, 3] \ast^\# [5, 8] = [5, 24]$$

$$[-1, 3] \ast^\# [5, 8] = [-8, 24]$$

$$[-1, 3] \ast^\# [-5, 8] = [-15, 24]$$

$$[-1, 3] \ast^\# [-5, -8] = [-24, 5]$$

Equality test:

$$[l_1, u_1] ==^\# [l_2, u_2] = \begin{cases} [1, 1] & \text{if } l_1 = u_1 = l_2 = u_2 \\ [0, 0] & \text{if } u_1 < l_2 \text{ or } u_2 < l_1 \\ [0, 1] & \text{otherwise} \end{cases}$$

Example:

$$\begin{aligned} [7, 7] &==^\# [7, 7] &= [1, 1] \\ [1, 7] &==^\# [9, 12] &= [0, 0] \\ [1, 7] &==^\# [1, 7] &= [0, 1] \end{aligned}$$



Inequality test:

$$[l_1, u_1] <^{\#} [l_2, u_2] = \begin{cases} [1, 1] & \text{if } u_1 < l_2 \\ [0, 0] & \text{if } u_2 < l_1 \\ [0, 1] & \text{otherwise} \end{cases}$$

Example:

$$\begin{aligned} [1, 7] <^{\#} [9, 12] &= [1, 1] \\ [9, 12] <^{\#} [1, 7] &= [0, 0] \\ [1, 7] <^{\#} [6, 8] &= [0, 1] \end{aligned}$$

## Monotonic abstract evaluation of expressions

For  $D \neq \perp$ ,

$$\llbracket x \rrbracket^\# D = D(x)$$

$$\llbracket n \rrbracket^\# D = [n, n]$$

$$\llbracket \square(e_1, \dots, e_n) \rrbracket^\# D = \square^\#(\llbracket e_1 \rrbracket^\# D, \dots, \llbracket e_n \rrbracket^\# D)$$

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Case  $e$  is  $x$ : since  $\rho \Delta D$  hence  $\llbracket x \rrbracket \rho = \rho(x) \Delta D(x) = \llbracket x \rrbracket^\# D$

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$$\text{Case } e \text{ is } \square(e_1, \dots, e_n): \quad \text{since each } \llbracket e_i \rrbracket \rho \Delta \llbracket e_i \rrbracket^\# D \text{ hence}$$

$$\llbracket \square(e_1, \dots, e_n) \rrbracket \rho = \square(\llbracket e_1 \rrbracket \rho, \dots, \llbracket e_n \rrbracket \rho)$$

$\Delta$

$$\square^\#(\llbracket e_1 \rrbracket^\# D, \dots, \llbracket e_n \rrbracket^\# D) = \llbracket \square^\#(e_1, \dots, e_n) \rrbracket^\# D$$

Finally, the **monotonic** abstract transformations induced by edges

$$\begin{aligned}
 & \llbracket l \rrbracket^\# \perp = \perp \\
 \text{For } D \neq \perp, & \quad \llbracket ; \rrbracket^\# D = D \\
 & \llbracket x = e; \rrbracket^\# D = D \oplus \{x \mapsto \llbracket e \rrbracket^\# D\} \\
 & \llbracket e \rrbracket^\# D = \begin{cases} \perp & \text{if } \llbracket e \rrbracket^\# D = [0, 0] \\ D & \text{otherwise} \end{cases}
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Clearly  $D \neq \perp$  here.

To check:  $\rho \Delta D \wedge \llbracket l \rrbracket \rho = \rho_1 \wedge \llbracket l \rrbracket^\# D = D_1 \implies \rho_1 \Delta D_1.$

Case  $l$  is ;

$$\rho_1 = \rho \Delta D = D_1.$$

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$$\rho_1 = \rho \oplus \{x \mapsto \llbracket e \rrbracket \rho\} \quad \text{and} \quad D_1 = D \oplus \{x \mapsto \llbracket e \rrbracket^\# D\}$$

As  $\llbracket e \rrbracket \rho \Delta \llbracket e \rrbracket^\# D$  hence  $\rho_1 \Delta D_1.$

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Case  $e$  is some condition  $e$

Since the transformation  $\llbracket e \rrbracket \rho$  is defined,

hence the expression evaluation  $\llbracket e \rrbracket \rho \neq 0$ , and  $\rho_1 = \rho.$

Since  $\rho \Delta D$ ,

hence the abstract expression evaluation  $\llbracket e \rrbracket^\# D \neq [0, 0]$ , and  $D_1 = D.$

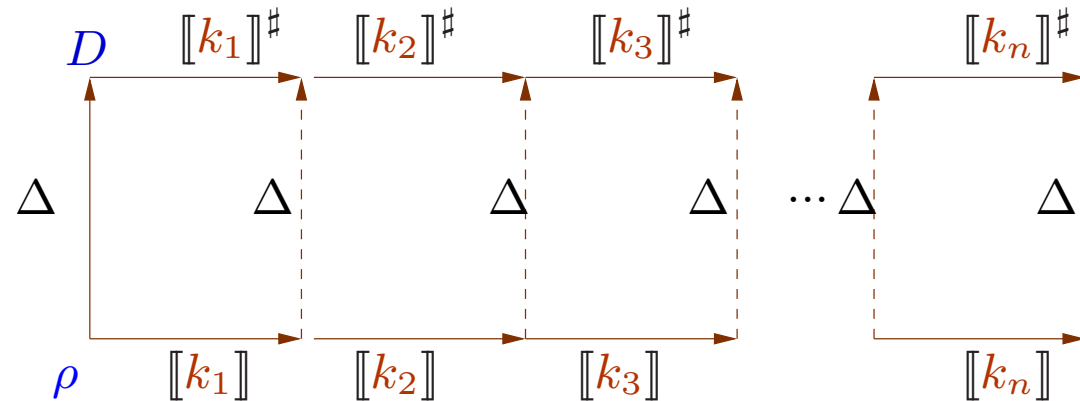
Recall, for a path  $\pi = k_1 \dots k_n$ ,

$$[[\pi]] \rho = ([[k_n]] \circ \dots \circ [[k_1]]) \rho$$

$$[[\pi]]^\# D = ([[k_n]]^\# \circ \dots \circ [[k_1]]^\#) D$$

We conclude from above:

if  $\rho \Delta D$  and  $[[\pi]] \rho$  is defined then  $[[\pi]] \rho \Delta [[\pi]]^\# D$ .



Merge over All Paths (MOP):

$$\mathcal{D}^*[v] = \bigsqcup \{ \llbracket \pi \rrbracket^\# \top \mid \pi : \textit{start} \rightarrow^* v \}$$

For any initial concrete state  $\rho$  and path  $\pi : \textit{start} \rightarrow^* v$ , if  $\llbracket \pi \rrbracket \rho$  is defined then

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Hence  $\mathcal{D}^*[v]$  abstracts all states possible at node  $v$ .

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To compute it, we use the **constraint system**:

$$\mathcal{D}[\textit{start}] \ \sqsupseteq \ \top$$

$$\mathcal{D}[v] \ \sqsupseteq \ \llbracket k \rrbracket^\# \mathcal{D}[u] \quad \text{for edge } k = (u, l, v)$$

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How are the two related?



Merge over All Paths (MOP):

$$\mathcal{D}^*[v] = \bigsqcup \{ \llbracket \pi \rrbracket^\# D_0 \mid \pi : \textit{start} \rightarrow^* v \}$$

Theorem:

Kam,Ullman 1975

Let  $\mathcal{D}$  be the smallest solution of the constraint system

$$\mathcal{D}[\textit{start}] \supseteq D_0$$

$$\mathcal{D}[v] \supseteq \llbracket k \rrbracket^\# \mathcal{D}[u] \quad \text{for edge } k = (u, l, v)$$

Then we have

$$\mathcal{D}[v] \supseteq \mathcal{D}^*[v] \quad \text{for every } v$$

$$\text{In other words: } \mathcal{D}[v] \supseteq \llbracket \pi \rrbracket^\# D_0 \quad \text{for every } \pi : \textit{start} \rightarrow^* v$$

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$$\llbracket \pi' \rrbracket^\# D_0 \sqsubseteq \mathcal{D}[u] \quad \text{induction hypothesis}$$

$$\llbracket \pi \rrbracket^\# D_0 = \llbracket k \rrbracket^\# (\llbracket \pi' \rrbracket^\# D_0)$$

$$\sqsubseteq \llbracket k \rrbracket^\# (\mathcal{D}[u]) \quad \text{monotonicity}$$

$$\sqsubseteq \mathcal{D}[v] \quad \mathcal{D} \text{ is a solution}$$

Question:

Does the constraint system give us **only an upper bound** ?

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In general **yes**.



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Now let's assume that all the functions  $[[k]]^\#$  are **distributive** ...

A function  $f : \mathbb{D}_1 \rightarrow \mathbb{D}_2$  is called

- **distributive**, when  $f(\bigsqcup X) = \bigsqcup\{f(x) \mid x \in X\}$  for all  $\emptyset \neq X \subseteq \mathbb{D}_1$ .
- **strict**, when  $f(\perp) = \perp$ .
- **total distributive**, when  $f$  is strict and distributive.

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$$f(x \cup y) = (x \cup y) \cap A \cup B$$

**Distributivity:**

$$= (x \cap A) \cup (y \cap A) \cup B$$

$$= (x \cap A \cup B) \cup (y \cap A \cup B) \quad \text{Yes}$$

Example 2:  $\mathbb{D}_1 = \mathbb{D}_2 = \mathbb{N} \cup \{\infty\}$ ,  $f(x) = x+1$ .

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Distributivity:  $f((1, 4) \sqcup (4, 1)) = f(4, 4) = 8 \neq 5 = f(1, 4) \sqcup f(4, 1)$  No

**Assumption:** All nodes  $v$  are reachable from the node *start*.

(Unreachable nodes can always be deleted.)

**Theorem:** If all the edge transformations  $\llbracket k \rrbracket^\#$  are distributive then  $\mathcal{D}^*[v] = \mathcal{D}[v]$  for all  $v$ .

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**Theorem:** If all the edge transformations  $\llbracket k \rrbracket^\#$  are distributive then  $\mathcal{D}^*[v] = \mathcal{D}[v]$  for all  $v$ .

**Proof:** We show that  $\mathcal{D}^*$  satisfies the constraint system.

(1) For the *start* node:

$$\begin{aligned}\mathcal{D}^*[start] &= \sqcup \{ [\pi]^\# D_0 \mid \pi : start \rightarrow start \} \\ &\supseteq [\epsilon]^\# D_0 \\ &= D_0\end{aligned}$$

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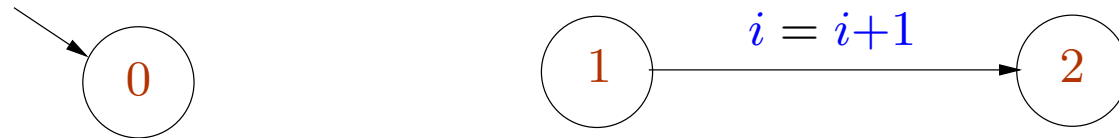
$$\begin{aligned}\mathcal{D}^*[start] &= \sqcup\{[\pi]^\# D_0 \mid \pi : start \rightarrow start\} \\ &\supseteq [\epsilon]^\# D_0 \\ &= D_0\end{aligned}$$

(2) For every edge  $k = (u, l, v)$

$$\begin{aligned}\mathcal{D}^*[v] &= \sqcup\{[\pi]^\# D_0 \mid \pi : start \rightarrow v\} \\ &\supseteq \sqcup\{[\pi'k]^\# D_0 \mid \pi' : start \rightarrow u\} \\ &= \sqcup\{[k]^\# ([\pi']^\# D_0) \mid \pi' : start \rightarrow u\} \\ &= [k]^\# (\sqcup\{[\pi']^\# D_0 \mid \pi' : start \rightarrow u\}) \\ &= [k]^\# (\mathcal{D}^*[u])\end{aligned}$$

since  $\{\pi' \mid \pi' : start \rightarrow u\}$  is non-empty.

The result does not hold in case of unreachable nodes.



We consider  $\mathbb{D} = \mathbb{N} \cup \{\infty\}$  with ordering  $0 \sqsubseteq 1 \sqsubseteq 2 \sqsubseteq \dots \sqsubseteq \infty$ .

Abstraction relation:  $n \Delta a$  iff  $n \leq a$ .

The abstract transformation for the second edge is defined by  $\llbracket k \rrbracket^\# a = a+1$ .

We choose  $D_0 = 5$ .

We have the constraints  $\mathcal{D}[0] \sqsupseteq 5$  and  $\mathcal{D}[2] \sqsupseteq \mathcal{D}[1]+1$ .

We have

$$\mathcal{D}^*[2] = \bigsqcup \emptyset = 0$$

$$\mathcal{D}[2] = 0+1 = 1$$